# MAC3 Series

# Digital controller Instruction Manual

Thank you for purchasing SHIMAX product. Please check that the product is the one you ordered. Please operate after you read the instruction manual and fully understand it.

# [Notice]

Please ensure that this manual is given to the final user of the instrument.

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# SHIMAX

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MAC3 F-1 AE January, 2005

#### Preface

This instruction manual is intended for those who will be involved in wiring, installation, operation and routine maintenance of the MAC3.

This manual describes the care, installation, wiring, function, and proper procedures regarding the operation of MAC 3.

Keep this manual on hand while using this device. Please follow the provided guidance.

## 1. Matters regarding safety

For matters regarding safety, potential damage to equipment and/or facilities and additional instructions are indicated as follows:

This mark indicates hazardous conditions that could cause injury or death of personnel. Exercise extreme caution as indicated.

# MARNING

This mark indicates hazardous conditions that could cause damage to equipment and/or facilities. Exercise extreme caution as indicated.

# **CAUTION**

This mark indicates additional instructions and/or notes.

## **NOTE**

## [**⚠ WARNING**]

MAC3 is designed for controlling temperature, humidity, and other physical subjects in general industrial facilities. It must not be used in any way that may adversely affect safety, health, or working conditions.

# - [A CAUTION]

To avoid damage to the connected equipment, facilities or the product itself due to a fault of this instrument, safety countermeasures must be taken before usage, such as proper installation of the fuse and the overheating protection device. No warranty, expressed or implied, is valid in the case of usage without having implemented proper safety countermeasures.

#### [ACAUTION]

• The mark on the plate affixed to the instrument:

On the terminal nameplate affixed to the case of your instrument, the mark is printed. This is to warn you of the risk of electrical shock which may result if the charger is touched while it is energized.

• The external power circuit connected to the power terminal of this instrument must have a means of turning off the power, such as a switch or breaker. Install the switch or breaker adjacent to the instrument in a position which allows it to be operated with ease, and with an indication that it is a means of turning off the power. Use a switch or breaker, which meets the requirements of IEC127.

#### • Fuse:

Since the instrument does not have a built-in fuse, do not forget to install a fuse in the power circuit to be connected to the power terminal. The fuse should be positioned between the switch or breaker and the instrument and should be attached to the L side of the power terminal.

Fuse Rating: 250VAC 0.5A/medium lagged or lagged type. Use a fuse which meets the requirements of IEC127

- Load voltage/current to be connected to the output terminal and the alarm terminal should be within the rated range. Otherwise, the temperature will rise and shorten the life of the product and/or result in problems with the product.
- Voltage/current that differs from input specification should not be connected to the input terminal. It may shorten the life of the product and/or result in problems with the product.
- Input, output of voltage pulse, and output of electric current are not insulated. Therefore, do not ground an adjusted power terminal when a ground sensor is employed.
- A signal wire's common mode voltage to ground (signal wires other than contact output including power supply and event) should be less than  $30V \, \mathrm{rms}$ ,  $42.4V \, \mathrm{peak}$ , and  $60 \, \mathrm{VDC}$ .

# 「▲ CAUTION」 -

- All the wires for the interior distribution, except for communication and contact output (including power supply and event), should be less than 30m in length. When the wire's length is 30m or more, or in the case of outdoor wiring, the suitable measure against a lightning surge is required.
- EMC standard (IEC61326) classifies MAC3 into Class A apparatus. Electromagnetic interference hay occur when MAC3 is used at a business district or in the home. Please use after taking

#### 2. Introduction

#### 2-1. Check before use

Before using MAC3, please check the model code, the exterior appearance and accessories. Also,

make sure that there are no errors, impairs and shortages.

Confirmation of model code: Check that the product you ordered is being delivered properly.

Check the model code of the main body case against the following code table.

MAC3A-	M	<u>C</u>	<u>F</u> -	E	<u>c-</u>	<u>D</u>	<u>H</u>	<u>T</u>	<u>R</u>	N
1	2	3	4	5	6	7	8	9	10	11

Item										
1. Series	s MAC3A-:96	5×96mm	size digi	tal control	ler					
	MAC3B-:48	3×96mm	size dig	ital control	ler					
2. Input	M:multi, V:	voltage, I:c	urrent							
3.Contro	ol Output 1 C:con	tact, S:volta	age puls	e, I:curren	t(4~20	mA),V:V	oltage	(0~10	IV)	
4. Powe	r Supply F-:90 - 264	V AC, L-::	21.6 - 20	5.4V DC/A	AC					
5. Event	Output N:none, E:H	Event Outp	ut $1 \cdot 2$	(two points	5)					
6.Contro	ol Output 2 · Event Out	put · Option	nal Sele	ction of Dl	[					
	N-:none, C	-:contact, S	S-:voltag	ge pulse, I-:	current	(4∼20m	A), V:	Voltag	e(0~1	0V)
	E-: Event C	Output 3(or	ne point)	, D-: exter	nal con	trol input	(DI4) (	one poi	nt	
7. DI	N:none,	D: external	l control	input (DI	1,2,3) t	hree point	s			
8. CT Ir	nput N: none,	H: CT Inp	out two j	points						
9. Analo	og Output N: none,	I: current (	4∼20n	nA)						
10. Com	munication N: none	e, R: RS485	5							
11. Progr	11. Program Function N: none, P: equipped									
Example of model code										
	<u>MAC3D-</u> 1	<u>M</u>	<u>C</u>	<u>F-</u>	<u>E</u>	<u>C-</u>	<u>D</u>	<u>T</u>	<u>N</u>	
	1	2	3	4	5	6	7	8	9	
Items										
1. Series	MAC 3 C	$72 \times 72$ mi	m size d	igital contr	oller					
	MAC3D-:	$48 \times 48$ mr	n size d	igital contr	oller					
2. Input	M:multi, V	': voltage, I	current:							
3.Control Output 1 C:contact, S:voltage pulse, I:current(4~20mA) V:Voltage(0~10V),										
4. Powe	4. Power Supply F-:90 - 264V AC, L-:21.6 - 26.4V DC/AC									
5. Event Output N:none, E: Event Output 1 · 2 (two points)										
6.Control Output 2 · Event Output · Optional Selection of DI										
	N-:none,	C-:contact,	S-:volta	ige pulse, I	-:currer	nt (4 $\sim$ 20r	nA) V	:Voltag	$ge(0\sim)$	10V)
	E-: Event	Output 3(c	one poin	t), D∹ exte	rnal co	ntrol input	(DI4)	one po	oint	

7. DI·CT Input N: none, D: external control input (DI1,2,3) three points, H:CT Input two points 8. Analog Output · Communication N: none, T: current (4~20mA), R: RS485

9. Program Function N: none, P: equipped

#### Check of accessories

Instruction manual: 1 set

NOTE : Please contact our agencies or business offices if you have any problem. We welcome any kind of inquiry such as defect of the product, shortage of accessory and so on.

#### 2-2. Caution for use

- (1) Do not operate the front panel keys with hard or sharp objects.
- Do not fail to touch keys lightly with a fingertip.
- (2) Wipe gently with a dry rag and avoid using solvents such as thinner.

## 3. Installation and wiring

3-1. Installation site (environmental conditions)

## [ ▲ CAUTION ]

Do not use this product under the following conditions.

- Otherwise, failure, damage and fire may occur.
- (1) Where flammable gas, corrosive gas, oil mist or dust generate or grow rife.
- (2) Where the temperature is below  $-10^{\circ}$ C or above 55°C
- (3) Where the humidity is over 90%RH or where condensation occurs.
- (4) Where high vibration or impact occurs
- (5) Where inductive interference may easily affect the operation.
  - Or, in the region of strong electric circuit area.
- (6) Where waterdrops or direct sunlight exists

sufficient measures.

(7) Where the altitude is above 2,000m.

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[NOTE] : The environmental conditions comply with the IEC664.

Installation category is  $\Pi$  and the pollution degree is 2.

#### 3-2. Mounting

(1) Machine the mounting hole by referring to the panel-cut illustration in Section 3-3.

(2) Applicable thickness of the mounting panel is  $1.2 \sim 2.8 \mathrm{mm}.$ 

(3) As this product provides mounting fixture, insert the product into the panel.

## 3-3. External dimension and panel cutout

MAC3 external dimensions (unit: mm)









MAC 3 B







MAC3 panel cutout (unit: mm)







MAC3C 72×72size



## MAC3D 48×48size



Note: Proximity attachment by a single hole is possible only in the case of horizontal direction.

When an apparatus that was attached in vertical direction is removed, a dedicated detachment tool is required.

3-4. Wiring

- MARNING J

ODo not turn on electricity while wiring to avoid an electric shock.

<sup>O</sup>Do not touch a terminal or live part while turning on electricity.

(1) Make sure that wiring operation is properly done in line with a terminal wire diagram of section 3-5.

(2) Choose a suitable compensation lead wire in the case of thermocouple input.

(3) In the case of resistance bulb input, resistance value of each lead wire must be less

 $5\Omega$  and that of three lead wires must be equal.

(4) Do not wires an input signal line inside of an electric wire pipe or a duct same with the

high voltage line.

(5) Shield wiring (single point grounding) is effective against static induction noise. (6) Wiring twisted at equal short intervals is effective against electromagnetic induction noise.



510 Ψ. - 22 RUN

(4) ENT (ENTRY/REGISTER)kev The setting data changed on each screen is determined (the decimal point of the minimum digit is also lighted off).

change is in progress. In PROG, used as a shift key between each step setting screens (Steps 1-25), lead screen. Also used as a shift key between lead screen in each mode screens.

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When a program control option is added, press Evi (ENT) key for three seconds on the screen of operation mode 1, then it jumps to the screen of operation Mode 2.

Press PMT key for 3 seconds on the output monitoring screen then the shift between manual output and automatic output is carried out.



Press the key for 3 seconds on the basic screen, then it shifts to FIX or PROG head screen.

Push at FIX-PROG and each mode screens' lead screen, then shifts to setting screen.

(5) RUN (RUN OPERATION/STOP)key

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Push for 3 seconds at STBY (control stop), then FIX or PROG control starts. Push for 3 seconds while FIX or PROG is in operation, then control is stopped.

#### 5. Description of screens

5-1. How to move to another screen

Basic Screen

$$\begin{array}{ccc} \mathcal{P} & = & \mathbb{E} \mathbb{M} & \text{3 seconds} & \to \mathcal{F}_{\mathcal{L}} & \text{(constant value control) lead screen of setting screens or } \mathcal{P} & \to \mathcal{P}_{\mathcal{L}} & \mathcal{P}_{\mathcal{D}} & \mathbb{G} & \mathbb{C} \\ \mathcal{G} & \leftarrow & \mathbb{M} & \text{3 seconds} & & \mathcal{S} & \mathcal{E} & \mathcal{E} \\ \end{array}$$

Press the 🔤 key for 3 seconds on a basic screen, then it shifts to the lead screen of Fig. (constant value control) setting screens, or to the lead screen of Prof. (program control) setting screens. Press the multiple key for 3 seconds on Fib or Prof. the lead screen of setting screens, then it shifts to the basic screen. The shift is also possible when the program option is added and Fib is chosen on the operation mode 2 screen. The shift is possible when the program option is added and *ProC* is chosen on the operation mode 2 screen.



Every time you press the www key on a basic screen, it shifts to each screen of the basic screens.

Press the mu key for 3 seconds on a basic screen, then it shifts to the lead screen of mode 1 screens.

Press the 🛋 key on the lead screen of mode 1 screens , then it further advances to mode 2, and mode 3. (Notes: If no corresponding option is found, the mode 4 - 9 is skipped)

Press the 👿 key on the lead screen of mode 1 screens , then it further advances to mode 9, and mode 8. (Notes: If no corresponding option is found, the mode 4 - 9 is skipped)

Press the 🛛 key for 3 seconds on the lead screen of mode 1 ~ 9 screens, then it shifts to the basic screen.

Press the BMT key on the lead screen of mode 1~ 9 screens, then it shifts to the first setting screen of each screens.

Press the 🔤 key on the the first setting screen of each screens, then it shifts to the next screen. Every time you press the 🔤 key, it shifts to the next setting screen.

## 5-2. Setting Method

To change settings, display an appropriate screen and change the setting (value or function) by pressing 🔊 or 💟 key.

On the output monitor screen of basic screens, you can change the control output from "Automatic" to "manual", and save its change of setting. Display the output monitor screen, and then press Im key for three seconds to shift from Automatic to Manual. Then by pressing 🛋 or 💌 key, you can adjust to the desirable output value. In this case, no need to press 🖭 key in order to determine the change of setting. Press 🖭 key for three seconds as well to shift back to Automatic. Excluding when a keylock is OFF, Automatic Automatic Automatic Automatic STBY (RST) and AT are in operation. In the case of two-output type, the switchover between automatic and manual is operatable through output 1 and output 2. The setting is altered simultaneously.

Output monitor		Output monitor	Output monitor
25		25	25
, 1000	three seconds -	→ ' :000 - ▲ or ▼ -	→ <b>′</b> 500
Automatic screen	RUN lamp lights up	Manual screen RUN lamp blinks	Manual screen RUN lamp blinks

#### 5-3. Power-on and initial screen display

At power-on, the display sectior	n shows each sc	reen of initial screens for one second , then m	noves on to the basic screen		
8888	Ēn	0	out !	out2	25
«Power-on»→ <b>8.8.8.8</b> .	ightarrow $ ho$ $ ho$ $ ho$	ightarrow .200 $ ightarrow$	$\mathcal{E}$ $ ightarrow$	ī —	) <b>(</b>
All LED light up	Input type	Upper limit & lower limit of measuring range	Out 1 type	💥 Out 2 type	Basic screen
		🕻 : Contact 🛛 🔓 : Voltage pulse	Current XOutput 2	Displays only optional a	addition.

#### 5-4. Explanation of each scre

(1) Basic Screens		
Basic Screen		Priority is given to DI when RUN is allotted to external control input. DI. Key operation cannot be
25	Executed SV initial value : Sensor input 0	performed unless allotment is canceled.
0	Linear input Lower limit of scaring range	When measuring range, a unit, scaling, and output characteristics are changed it is initialized and
	Setting range: Sensor input Within measuring range	Sととり (ーSと) is displayed.
INU key	Linear input With in scaring range	Press 🖭 key for 3 seconds, then it shifts to Action mode2 screen, when the program control
	Within SV limiter besides	option is added on this screen, FIX (constant value control) $\leftarrow \rightarrow$ PROG (program control)
Targeted	value (PV) is displayed on the upper row as four–digit ,and target d	switchover is possible choose.
valu	e (SV) is displayed on the lower row also as four–digit. (Notes:hereinafter,	Choose a program,then Monitor LED's PRG lights up.
measured value and targeted value are referred to as $"PV"$ and $"SV")$		Action mode1 screen Action mode2 screen
At the	e time of FIX, execution SV is displayed and change of setting is possible.	$25 \rightarrow$ $m$ three seconds $25 - M$ $M \rightarrow 25$
✓ PROG <sup>*</sup>	's SV is just displayed ,and change of setting is impossible.	5とちちく〔.three seconds チごらく 🔽 🔤 🦻 アーロン
Action Mode 1 scr	een	$r5t \leftarrow c$ , three seconds PRG LED lights up
<b>25</b> Initial value:: <b>5<i>E</i> <b>b <i>J</i></b>(stanby)(Initial value at the time of constant value control)</b>		Press 🔤 key for 3 seconds on Action mode2 screen, then it returns to Action mode1 screen.
SEBS	-52 (reset) (Initial value at the time of program control)	Action mode2 screen is not displayed without a program option.
Setting range:: <b>5 - 5 - 5 - 5 -</b> ) Control stop [Output OFF (0%)] operation		When PROG is allotted to DI, DI is given priority. Key operation cannot be performed unless
MNU key	conduct of control operation	allotment is canceled.

5

Choose run (RUN) by 💌 key. Decide by 🔤 key, then Monitor LED's RUN lights up to start control operation.

Choose 5253(-52)by key, Decide by Evil key, hen Monitor LED's RUN lights off

and becomes control stop [Output OFF (0%)] conducting.

Press we key on Action mode1 screen, then it shifts to output 1 monitoring screen.

Output 1 monitoring screen 25 manual output setting range: :0.0-100.0% (within output limiter) ' **ICCC** At the time of automatic output, monitor display only. ₩ key Refer to Item 5–2 about automatic ⇔ manual switchover,and setting method at the time of manual operation. A manual output is canceled when an operation mode is made into 5253 (~52). When a power source is intercepted and re-switched on, it returns to the condition just before intercepting When  $\vec{n} R n_{u}$  is allotted to DI, DI is given priority. Automatic ma  $\Leftrightarrow$  manual switchover is not performed with key operation, and only the output value at the time of manual operation can be changed. Output 2 monitoring screen 25 , 1000 Contents are the same with that of an output 1. we key Output 2 monitoring screen displays only when output 2 option is added. CT1 current monitoring-screen 25 Current display range: 0.0-55.0A - 500 Displays at the time of CT input option addition, and the current value detected by CT sensor is displayed. www key Current value is displayed. CT2 current monitoring screen 25 - 300 Contents are the same with that of an output 1. 💵 key Monitoring screen of step's remaining time period 25 99:59 Displays while program is in operation if program option is added. 📾 key Step No. in progress and remaining time are displayed by turns. (In  $\infty$  setting, step N0. and  $\mathbf{P}$  are displayed by turns) A remaining time and an elapsed time is switchable by pressing the EM key for 3 seconds. (Switchover is interlocked with the number of times of next screen pattern.) Decimal point of the minimum digit lights up in displaying elapsed time, This screen is not displayed without a program option.Not displayed in the state of program RST and FIX neither. Monitoring screen for the remaining repeating time of pattern 29 9999 Being displayed while program is in operation, when the program option is added, On-going step No. and the remaining repeating time of pattern are displayed by turns.  $\mathbb{H}$  key (In  $\infty$  setting, step No. and  $\mathbb{P}$  are displayed by turns) A remaining time and actually performed times are switchable by pressing the EMT key for 3 seconds. (Switchover is interlocked with front screen step time.) The decimal point of the minimum digit lights up when actually performed times being displayed. This screen is not displayed without a program option.Not displayed in the state of Program RST and FIX neither. PID No. monitoring screen 25 P2\_: Chosen PID No. is displayed when FIX is in operation. PID No. chosen at each step and on-going step No. are displayed by turns when PROG key is in operation. PID No. of output 1 is displayed in the first digital, and PID No. of output 2 is displayed in the third digital. The third digital is shown as \_ when there is no output 2 option. This screen is not displayed in the state of STBY (RST). HOLD (temporary stopping) execution screen Initial value:: oFF Hold Setting range:: oFF.on oFF While HOLD is executed, on the basic screen, SV value and HoLD is displayed by turns . If switched  $\Box$   $\neg$  while PROG is in operation , the operation temporary stops with as of then step time and SV value. While HOLD is in execution , SV value and  $\, {m {\cal H}}$ **a** is displayed by turns in basic screen.

# 5HCP (skip)is unable to perform while HOLD is in execution. When HoLd is allotted to DI, DI is given priority. Execution and release of HOLD with key operation is unable to perform. This screen is not displayed without a program option.Not displayed in the state of program − 5 and FIX neither. SKIP (skip) execution screen SHEP Initial value:: oFF oFF Setting range:: oFF.on SKIP (skip) is the function that makes to end the on-going step compulsorily, and is to shift to the following step. The next step starts instantly, if performed. When SKIP is continuously performed, about 1 second interval is required from execution to the next one. Even if SKIP is allotted to DI, execution is able to perform with DI and key operation. Makey SKIP cannot be performed while HOLD is in operation. This screen is not displayed without a program option. Not displayed in the state of program -5E and FIX neither. AT (Auto Tuning) execution screen RĿ Initial value:: OFF oFF Setting range:: oFF.on MENU kev AT is performed by ON selection ,and canceled by OFF selection. Not displayed at the time of STBY(RST), a manual output, and P(proportional band) =OFF. Except in the setting of keylock OFF, AT is unable to perform in scale over. (At the time of DI allotment, execution of AT by DI can be performed .) Even in such a case,halfway release is performed on this screen. Release of AT, STBY(RST), EV operating point, setting of keylock, and mode 5 $\,\sim\,$ 9screen are operateable with key. Except in th setting of AT normal end, execution of AT is canceled compulsorily at the time of STBY(RST) selection and AT release setup. EV1 (event 1) operating-point setting screen E8 I -Initial value: upper limit absolute value measuring range Scaling upper limit 1200 lower limit absolute value measuring range Scaling lower limit upper limit deviation 2000 lower limit deviation **-4999** MENU kev within deviation outside deviation 2000 CT1 or CT2 00 0 guarantee Setting range: upper limit absolute value within measuring range within scaling limit lower limit absolute value within measuring range within scaling limit upper limit deviation -4999~2000 unit lower limit deviation **3999~2000** unit within upper-lower limit deviation *B***~2000** unit outside upper-lower limit deviation **B~2000** unit CT1 or CT2 0~50.0A The operating point of the alarm type allotted to EV1 is set up. No option, No display when non, So, run, SEP, P.E, End, Hold, ProG, d\_SL, and u\_SL are allotted to EV1. The operation mode of each deviation alarm is Effective at the time of automatic output Each deviation alarm serves as PV's deviation to Execution SV Event operation other than each deviation alarm is always effective. EV2 (event 2) operating-point setting screen *E85* 0 Initial value, setting range, contents are the same with EV1 MENU key EV3 (event 3) operating-point setting screen E83 0 Initial value, setting range, contents are the same with EV1 MENU kev When EV3 option is added, event 3 is displayed as the same contents with EV 1 and 2, irrespective of EV 1 and 2.

insufficient time of flat step.

Controls is performed with SV value at the time of stopping,while HOLD is in execution

step or to con

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of the step is performed based on a program.

HOLD is used in order to perform AT in the middle of an in

```
Latching release screen
 LRch
                        Initial value::-52 /
 -5E /
                       Setting range:: -5 - 1 release EV1
                               -522 release EV2
                                     -523 release EV3
         MENU kev
                                RLL release all EVs at a time
              On the latching setting screen of each EV mode, - 5 No. and RLL which chose
              00
               are displayed. If latching is on, once EV is outputted, EV output state is maintained even
              if EV is in the state of OFF. When EV is in a latching state, decimal point of the minimum
              digit blinks, and it shows that release of EV is possible. If EVT key is pressed, EV is released
              and a decimal point lights off.
         However, release is impossible when a state is in EV power range.
Return to basic screen
  (2) FIX (constant value control) setting screens
       At the time of no program option and with program option and F , is chosen on Action
       mode2 screen of basic screens,lead screen of FIX setting screens is displayed when Err key is
       pressed for 3 seconds.
       If EVT key is pressed for 3 seconds on lead screen, it returns to basic screen.
                                      lead screen of FIX setting
       basic screen
         25
                            - \bowtie three seconds \rightarrow F<sub>2</sub>-
          0
                        \leftarrow methree seconds - 582
 FIX lead screen
 FES
  SEE No setting on this screen.
          EVT key Press EVT key, then it shifts to the first setting screen SV1 setting screen.
 SV1 setting screen
                           Initial value : At the time of sensor input 0
 58 :
           0
                                       linear input time scaling lower limit
                           Setting range: sensor input time within measuring range
          new key
                                  linear input time within scaling range
                                  Moreover, within limit of SV limiter.
         When SV1 is Execution SV, being reflected in basic screen.
         Being initialized when measuring range, unit, and scaling are changed.
 SV1 output1 PID No. setting screen
  lo IP
                          Initial value : 1
                        Setting range:1, 2, 3
          we when SV1 is Execution SV,PIDNo. that will be used for control of output 1
                    is chosen from 1 \sim 3.
 SV1 output2 PID No. setting screen
  1022
                            Initial value:1
                        Setting range:1,2,3
         When SV1 is Execution SV,PIDNo. that will be used for control of output 2 is
                 chosen from 1 \sim 3.
              Displayed when output 2 option is added.
 SV2 setting screen
  582
                            Initial value: same with SV1
      \Box
                        Setting range: same with SV1
         MENU key
         Displayed when SV2 is allotted to DLWhen terminal of allotted DI short-circuits, it becomes
              Execution SV.
               When SV2 is Execution SV, it is reflected in basic screen.
              Being initialized when measuring range, unit, and scaling are changed.
 SV2 output 1 PIDNo. setting screen
 20 IP
                            Initial value:1
                                                                                                             Please refer explanation
                        Setting range:1,2,3
       !
                                                                                                             of program sequence
            Displayed when SV2 is allotted to DI.
           When SV2 is Execution SV,PIDNo. that will be used for control of output 1 is
```

Displayed when output 2 option is added. SV3 setting screen 583 Initial value: same with SV1 0 Setting range: same with SV1 key Displayed when SV3 is allotted to DI.When terminal of allotted DI short-circuits, it becomes Execution SV. When SV3 is Execution SV, it is reflected in basic screen. Being initialized when measuring range, unit, and scaling are changed. SV3 output 1 PIDNo. setting screen 30 IP Initial value:1 Setting range:1,2,3 ! MENU key Displayed when SV3 is allotted to DL. When SV3 is Execution SV,PIDNo. that will be used for control of output 1 is chosen from 1~3. SV3 output 2 PIDNo. setting screen 302P Initial value:1 Setting range:1,2,3 1 key Displayed when SV3 is allotted to DL. When SV3 is Execution SV,PIDNo. that will be used for control of output 2 is chosen from  $1 \sim 3$ Displayed when output 2 option is added. SV4 setting screen 584 Initial value: same with SV1 0 Setting range: same with SV1 key Displayed when SV4 is allotted to DL. When terminal of allotted DI short-circuits, it becomes Execution SV. When SV4 is Execution SV, it is reflected in basic screen. Being initialized when measuring range, unit, and scaling are changed. SV4 output 1 PIDNo. setting screen 40 iP Initial value:1 Setting range:1,2.3 ! 📾 key Displayed when SV4 is allotted to DI.. When SV4 is Execution SV,PIDN0. that will be used for control of output 1 is chosen from 1~3. SV4 output 2 PIDNo. setting screen 402P Initial value:1 : Setting range:1,2,3 we key Displayed when SV4 is allotted to DI.. When SV4 is Execution SV,PIDNo. that will be used for control of output 2 is chosen from 1~3. Displayed when output 2 option is added. Return to FIX lead screen (3) PROG (program control) setting screens Press Err key for 3 seconds, lead screen of the PROG setting screens is displayed, When program option is added and *Prof* is chosen on Action mode2 screen of basic screens. If me key is pressed for 3 seconds on lead screen, it returns to basic screen. Basic screen lead screen of the PROG setting screens 25 - In three seconds  $\longrightarrow ProG$  $\leftarrow$  me three seconds -- PE\_ : 0 Press INT Key for 1 second it will move to Program pattern 2 screen, and Press INT key 1 second It will move to program pattern 1,2, 4, The number of setting in the program pattern screen can be changed 1-4 to the number of program pattern.(1=pattern 1,2= pattern 1 & 2, 4= pattaern 1 to 4) Only the pattern you did program pattern setting screen will be indicated.  $\mathbf{r}$  $P_{\neg o} \mathcal{G} \ \texttt{Intermation} \ \texttt{Pro} \mathcal{G} \ \texttt{Intermation} \ \texttt{Pro} \mathcal{G} \ \texttt{Intermation} \ \texttt{Isecond} \rightarrow P_{\neg o} \mathcal{G} \ \texttt{Intermation} \ \texttt{Isecond} \rightarrow \texttt{Pro} \mathcal{G} \ \texttt{Intermation} \ \texttt{Isecond} \ \texttt{Intermation} \ \texttt{Pro} \mathcal{G} \ \texttt{Intermation} \ \texttt{Intermation}$ ↓<sup>₽</sup>٤\_ / PE\_2 ~ PE\_3K PE\_4 ~ S\_ñd S\_ñd S\_ñd S\_nd 58 58 58 58 V 🖻 MENU

5558

End

V 🖻

Pene

*□* ↓ ₪

25

5558

End

Pene

↓ 🔤

CURE 📼

oFF

25 V ®

0

5558

0

25

End

 $\sqrt{100}$  MeNU

CURE

oFF

Pene

 SV2 output 2 PIDNo. setting screen
 /

 Co2P
 Initial value:1

 Setting range:1,2,3
 CoRE\_MI

 Image: key Displayed when SV2 is allotted to DI.
 OFF

 When SV2 is Execution SV,PIDNo. that will be used for control of output 2 is chosen from 1~3.
 7

chosen from  $1 \sim 3$ .

Program basic setting screens Step 1 setting screens ~ Step 40 setting screens Program basic setting screens Lead screen Pro5 No setting on this screen  $\nabla$ **SEE** Press key to shift to step 1 lead screen. Press ▼ key to shift to step 40 lead screen. \_ :← will key Press will key to shift to the first setting screen start mode setting screen. Start mode setting screen S\_Ād Initial value: **PB**(PV) 58 Setting range: **5**8 (SV), **P**8(PV) This setting screen can decide if the start set point of program control should be PV, or MENU we should be the start SV which is set on the next screen. When PV is chosen, and when PV is closer to the set point of Step1 than start wasting SV,time is omissible. MENU Start SV setting screen 5558 Initial value : At the type of sensor input 0 0 linear input type scaling lower limit Setting range: sensor input type within measuring range MENU MENU key linear input type within scaling range Moreover, within limit of SV limiter. When SV is chosen on start mode setting screen, this screen's set value becomes start set point. MENU The basic screen SV display at the time of Program RST is the value set on this screen. Termination step setting screen End Initial value: 40 9 Setting range: 1~40 steps 🛯 key Pattern termination step No, of program control is set. Number of execution Setting screen for repeating of program pattern Pene Initial value:1 same setting item screen. Setting range:  $1 \sim 9999$  times,  $\infty$ 1  $\psi$  🖻 key The number of execution of a program pattern is set. Gurantee soak zone Step1 SV setting screen Initial value:OFF CURE. oFF Setting range:OFF,1~2000 Digits(Time unit belong to the Time unit setting screen) we key In case deviation of step SV of level step PV remains, the step does not move to the next step until PV reach to the SV. Time unit setting screen Initial value: 77:55 (minute:second) 6\_00 Setting range: AA:55, HH:AA, HHH.H āā:55 key This decides if unit of the execution time set up at each step is minute: second hour minute or hour. To program basic setting screens Lead screen About PV start In start mode, when PV is chosen, and when PV is closer to the set point of Step1 than start SV, wasting time is omissible. [example]:PV at the time of "RST is 30°C, Start SV is 0 °C, Step 1's attainment SV 100 °C, Execution time of Step1 is 60 minutes Start at start SV,attainment time is 60 minutes. When starts at PV, 100-30=70°C ,therefore 60 minutes x70%= 42 minutes = 18 minutes' shortening However, depending on the spatial relationship between PV, Start SV, and attainment SV, it may become SV start or Step1 may be skipped. (1) case of SV start PV≦S\_SV(start SV) < 1\_SV (step1 attainment SV) PV≧S\_SV>1\_SV 1\_SV PV S\_SV S SV PV 1\_SV Step 1 Step 2 Step 1 Step 2 (2)When Step 1 is skipped and progresses to Step 2

S\_SV < 1\_SV < PV  $S_SV > 1_SV > PV$ PV=1\_SV



8

Screen sequence of step 1 setting screens  $\sim$  step 40 setting screens are as follows.



In each step setting screen, next to number, \_for Steps 1~9, for 10~ 19 - for 20~ 29, 30  $\sim$ 39 and 40 = are assained to distinguish each of them.

(Step 1 SV = 1\_58, step 12SV = 2-58, step 23SV= 3-58, and step 34 4 - 58) If the EMT key is pressed at each step lead screen, it shifts to SV setting screen of each step. If the 📾 key is pressed on SV setting screen, it shifts to execution time setting screen of each step. After that, if me key key is pressed, then it shifts to output 1PIDNo., output 2PIDNo., and lead screen. Moreover, it is if Err key is pushed for 1 second on each setting screen, it advances to the next Step No.'s

 $(1_SV \rightarrow 2_SV \cdots \rightarrow 0 = SV \rightarrow 1_SV)$ 

Step 1 is explained, since all the setting content of each step are same.

1_58	58 Initial value : At the time of sensor input 0					
·c	At the time of linear input scaling lower limit					
	Í	Setting range : At the time of sensor input within measuring range				
	MENU key	At the time of linear input scaling within the limits				
	Noy	Within limit of SV limiter and yet				
	Attainment set value of Step 1 is set.					
		tialized when measuring range, unit, and scaling are changed.				
Step 1 ex	/	time setting screen				
		Initial value: 00:01				
		Setting range: 00:00 to 99:59 (minute: second, hour : minute)				
ارو		$0.1-999.9$ (hour) and $\infty$ (infinity)				
	MENIL KOV	Execution time of Step 1 is set.				
	KCy					
Step1 out	V tout 1 DID	No cotting corpor				
i_ :P	1 output1 PIDNo. setting screen PIDITE Initial value:1					
'_'',	Setting range:1~3					
	PIDNo. used in Step1's control output 1 is chosen.					
	FILM, used in Steph's control output this chosen.					
	KCy					
Stop1 out	V tout 2 DIF	DNo. setting screen				
<i>1_21</i>	-	Initial value:1				
1-2-		Setting range:1~3				
	kov E	PIDNo. used in Step1's control output 2 is chosen.				
	кеу г	10140. used in Stept's control output 2 is chosen.				
	Dianlaya	d uhan autrut 2 antion is added				
To ctor <sup>1</sup>	↓ Displayed when output 2 option is added. To step1 lead screen					
TO Step1	icau sure					

#### (4) Mode 1 screens

#### Mode 1 lead screen

Fress we key for 3 seconds on basic screen, then displayed

1  $\fbox{\sc m}$  key No setting on this screen. Press the  $\fbox{\sc m}$  key, then it shifts to the first setting screen, keylock setting screen.

# Keylock setting screen

LocY Initial value: \_FF oFF Setting range: OFF. I. 2. 3. 4 MENU key Conly change of Execution SV (basic screen) and keylock is possible. Possible to change numerical value value manualy ,and key lock level **3** Only change of a keylock is possible. └ Only change of a keylock is possible It can be locked № key Notes: Even when keylock is set as 1 and 2, manual output value is possible to change.

•	
SV limiter low	er limit setting screen
58_L	Initial value: measuring range lower limit
0	Setting range: measuring range lower limit value $~$ measuring range upper limit value $-1$
MENU K	ey And <b><i>LL</i></b> (SV display turn off)
Low	ver limit value of target value is set .
	When upper limit value is smaller than lower limit value, the value compulsorily becomes
	lower limit value +1.
$\downarrow$	When you choose 占 🖌 pressing 💿 at lower limit value ,the SV display tum off at
	basic screen. But it will turn on at the setting screen.
SV limiter upp	er limit value setting screen
58_H	Initial value: measuring range upper limit
1200	Setting range:SV limiter lower limit value $+1^{\sim}$ measuring range upper limit value
MENU k	ey Setting upper limit value of target value is set.
$\downarrow$	
Return to mo	de1 lead screen.
5) Mode 2 scr	eens
Mode 2 lea	d screen
ñodE	Press 🛦 key in mode1 lead screen, or press 🕠 key in mode3 lead screen,
2	then being displayed.
ENT	key If 🔤 key is pressed, it shifts to the first setting screen PV offset correction screen.
$\downarrow$	
PV offset co	rrection (PV bias) setting screen
P8_0	Initial value:0
0	S etting range:—500~500 Digits
MENU	key Used for correction of input errors such as sensor.
If	f offset correction is performed, control is also performed with the corrected value
$\downarrow$	
PV gain corre	ection setting screen
P8_C	Initial value:0.00
0.00	Setting range: ±5.00%
HENU key	Maximum input value is corrected within limit of $\pm 5.00\%$ of measuring range.
	If corrected, inclination of spang changes in straight line which connects zero point and
	correction maximum value.
$\downarrow$	
PV filter sett	ing screen
P8_F	Initial value:0
0	Setting range: 0 $\sim$ 9999 seconds
MENU	key When input change is violent or noise is overlapped, used in order to ease the influences.
	In 0 second setting, filter does not function.
v Mesuring range	e setting screen
-8-6	Initial value: multi H2, voltage H1, current AR1
ט יא	Setting range: Chosen from 5–5.measuring range code table.
, ,   1900	
	Combination of input type and measuring range is set by code.
	oonnomaaloon on milput type and measuring range is set by code.

```
Input scaling lower limit value setting screen
Scil
                                 Initial value:0.0
   0.0
                              Setting range: -1999 ~ 9989 digits
                      Scaling lower limit value at the time of linear input is set up.
       MENU kev
Input scaling upper limit value setting screen
Sc_H
                               Initial value:100.0
   100.0
                              Setting range: -1989 \sim 9999 digits
        📾 key Scaling upper limit value at the time of linear input is set up.
             NOTE: Suppose that the difference between a lower limit value and upper limit value is 10
                      or less,or over 10,000. In this setting, upper limit value is compulsorily changed
                      into that of +10 or \pm 10000 count. Upper limit value cannot be set as lower limit
                      value of +10 count or less,or that of over 10,000 count.
Input scaling Decimal point position Setting screen
dР
                Initial value: the first place after decimal point (0.0)
   0.0
                 Setting range: no decimal point 0~the third place after decimal point(0.000)
```

Decimal point position of input scaling is set . new key NOTE: The screen of input scaling serves as a monitor at the time of a sensor input. Setting change cannot be performed.

Return to mode 2 lead screen.

```
(6) Mode 3 screens
```

#### Mode 3 lead screen

## Restart No setup

3 If Err key is pressed, it shifts to the first setting screen, output 1 proportional band  $\mathbb{P}$  key setting screen. In this screens, PID which can be used in output 1, 1 ~3 related Items and soft start of output 1, and proportional period output characteristics are set up.

Output 1 PID1 proportional-band (P) setting screen

1\_P 1 Initial value:3.0% 30 Setting range:OFF, 0.1 ~ 999.9% MENU key When performing auto tuning, no necessity for a setting basically. If OFF is chosen, it becomes ON-OFF (two positions) operation.

Output 1 PID1 Integral time (I) setting screen

```
1_2 1
                       Initial value: 120 seconds
```

```
120
🕬 key
```

Setting range: 0FF, 1~6000 seconds

```
When performing auto tuning, no necessity for a setting basically.
This screen is not displayed at the time of ON-OFF operation.
Becomes P operation or PD operation in I=OFF setting.
```

Output 1 PID1 Derivative time (D) setting screen

1\_01

Initial value: 30 second 30 Setting range: 0FF, 1~3600 seconds MENU key

When performing auto tuning, no necessity for a setting basically. This screen is not displayed at the time of ON-OFF operation. Becomes P operation or PI operation in D=OFF setting.

Output1 PID1 manual reset setting screen lār l Initial value:0.0

0.0

9

MENU key

```
Setting range: -50.0~50.0%
```

```
The offset correction at the time of I=OFF ( P operation,PD operation]) is performed.
This screen is not displayed at the time of \ensuremath{\mathsf{ON-OFF}} operation.
```

Output 1 PID1 differential

re unit setting screer

 $\sqrt{}$ 

Temperatu

```
18F 1
                          Initial value: 5
   5
                       Setting range: 1 ~999 unit
   🕬 key
       The differential gap at the time of ON-OFF operation is set.
      Displayed at the time of P=OFF ( ON-OFF operation) setup.
```

Output1 PID1 minimum limiter setting screen IoL I Initial value:0.0 0.0 Setting range: 0.0~99.9% we output lower limit value of output 1 PID1 is set up. Note: At the time of STBY (RST) and scale over output, limiter value is disregarded. Output 1 PID1 maximum limiter setting screen 10H 1 Initial value:100.0 1000 Setting range: output limiter lower limiter values +0.1~100.0% key Upper limit value of output 1 PID1 is set . Output 1 PID2 proportional band (P) setting screen 1\_22 Initial value:3.0% 3.0 Setting range: OFF, 0.1~ 999.9% key Content is the same with output 1 PID1. Output 1 PID2 integral-time (I) setting screen 1\_22 Initial value: 120 seconds 120 Setting range: 0FF, 1~6000 seconds key Contents is the same with output 1 PID1. Output 1 PID2 derivative-time (D) setting screen 1\_02 Initial value: 30 seconds 30 Setting range: 0FF, 1~ 3600 seconds www.key Contents is the same with output 1 PID1. Output 1 PID2 manual reset setting screen 12-21 Initial value: 00 0.0 Setting range: -50.0~50.0% New Key Contents is the same with output 1 PID1. Output 1 PID2 differential gap setting screen 1825 Initial value: 5 5 Setting range: 5~999 unit New Key Contents is the same with output 1 PID1. Output 1 PID2 minimum limiter setting screen IoL2 Initial value:0.0 Setting range:0.0~99.9% 00 🕬 key Contents is the same with output 1 PID1.  $\sqrt{}$ Output 1 PID2 maximum limiter setting screen IoH2 Initial value: 100.00 1000 Setting range: output limiter lower limit value +0.1~100.0% key Contents is the same with output 1 PID1. Output 1 PID3 proportional band (P) setting screen :\_P3 Initial value: 3.0% 3.0 Setting range:OFF, 0.1 ~ 999.9% key Contents is the same with output 1 PID1. Output 1 PID3 integral-time (I) setting screen 1\_23 Initial value: 120 seconds 120 Setting range: 0FF, 1~ 6000 seconds key Contents is the same with output 1 PID1. Output 1 PID3 derivative time (D) setting screen Initial value: 30 seconds 1\_83 Setting range: 0FF, 1~3600 seconds 30 New Key Contents is the same with output 1 PID1.  $\mathbf{V}$ Output 1 PID3 manual reset setting screen IA-3 Initial value:0.0 0.0 Setting range: -50.0~50.0% New kev Contents is the same with output 1

Output 1 PID3 minimum limiter setting screen Initial value: 0.0 ioL3 0.0 Setting range: 0.0~99.9% key Contents is the same with output 1 PID1. Output 1 PID3 maximum limiter setting screen IoH3 Initial value: 100.0 100.0 Setting range: output limiter lower limit values +0.1~100.0% key Contents is the same with output 1 PID1. Output 1 soft starting time setting screen ISoF Initial value: OFF oFF Setting range:OFF, 0.5~120.0 seconds (setting resolution 0.5 second) This is the function that eases change of output at the time of a power-on and startup. we key Does not function at the time of OFF setup. Output 1 proportional periodic time setting screen 1\_0[ Initial value: Contact output 30.0 seconds 30.0 Voltage pulse output 3.0 seconds MENU key Setting range:  $0.5 \sim 120.0$  seconds (setting resolution 0.5 second) Proportional periodic time of output 1 is set. Not displayed when output 1 is current. Output 1 characteristics setting screen IRct Initial value:- 🗛 rR Setting range:- R. dR key Characteristics of control output is chosenfrom **~** *R* (heating characteristics) and  ${\it dR}$  (cooling characteristics) Return to mode 3 lead screen (7) Mode 4 screens Mode 4screens is the setup screens of output 2 option. Not displayed when option is not added. Mode 4 lead screen ποσΕ No setup Y Press INT key , then it shifts to the first setting screen, output 2 proportional band 1 ENT key setting screen. On this screen, PID1~3 related items that can be used in output 2, soft start of output 2,and proportional period output characteristics are set. Output 2 PID1 proportional band (P) setting screen 2\_P ( Initial value:3.0% Setting range:OFF, 0.1 ~ 999.9% 3.0 key Contents is the same with output 1 PID1. Output 2 PID1 integral-time (I) setting screen 2\_2 / Initial value: 120 seconds 120 Setting range: 0FF, 1~ 6000 seconds New key Contents is the same with output 1 PID1. Output 2 PID1 derivative-time (D) setting screen 1 6\_5 Initial value: 30 seconds 30 Setting range: 0FF, 1~3600 seconds key Contents is the same with output 1 PID1. Output 2 PID1 dead-band setting screen 299 1 Initial value:0 0.0 Setting range: -1999~5000 unit MENU key Output 2's operation zone to output 1 is set with dead- band. Output 2 PID1 differential-gap setting screen 28F : Initial value:5 5 Setting range: 1~999 unit we key Contents is the same with output 1 PID1. Output 2 PID1 minimum limiter setting screen 2-1 1 Initial value: 00

rene key C	contents is the same with output 1 PIDT.	COL 1	
$\downarrow$		0.0	Setting range: 0.0~99.9%
Output 1 PID3 differ	rential gap setting screen	1990 key	Contents is the same with output 1 PID1.
18F3	Initial value:5		
5	Setting range:1~999 unit	$\checkmark$	
V 🔤 key C	Contents is the same with output 1 PID1.		
		10	

Output 2 PID1 maximum limiter setting screen 20H I Initial value:100.0 100.0 Setting range: output limiter lower limit values +0.1~100.0 % key Contents is the same with output 1 PID1. Output 2 PID2 proportional-band (P) setting screen 2-92 Initial value:3.0% 3.0 Setting range: OFF, 0.1~ 999.9% key Contents is the same with output 1 PID1. Output 2 PID2 integral-time (I) setting screen 5772 Initial value: 120 seconds 120 Setting range: 0FF, 1~6000 seconds key Contents is the same with output 1 PID1. Output 2 PID2 derivative-time (D) setting screen 2-95 Initial value: 30 seconds 30 Setting range: 0FF, 1~3600 seconds key Contents is the same with output 1 PID1. Output 2 PID2 dead-band setting screen 2992 Initial value:0.0 Setting range:—50.0**~**50.0% 0.0 www. Key Contents are the same as output 2PID1 dead-band setting screen. Output 2 PID2 differential-gap setting screen 23F2 Initial value: 5 5 Setting range: 1~999 digits New Key Contents is the same with output 1 PID1 Output 2 PID2 minimum limiter setting screen 2015 Initial value: 0.0 0.0 Setting range: 0.0~99.9% we key Contents is the same with output 1 PID1. Output 2 PID2 maximum limiter setting screen 20H2 Initial value:100.0 100.0 Setting range:output limiter lower limit values+0.1~100.0 % key Contents is the same with output 1 PID1. Output 2 PID3 proportional-band (P) setting screen 2\_P3 Initial value:3.0% 30 Setting range:OFF, 0.1~999.9% key Contents is the same with output 1 PID1. Output 2 PID3 integral-time (I) setting screen 2\_23 Initial value: 120 seconds Setting range: 0FF, 1~6000 seconds 120 key Contents is the same with output 1 PID1. Output 2 PID3 derivative-time (D) setting screen 5-93 Initial value: 30 seconds Setting range: 0FF, 1~3600 second 30 key Contents is the same with output 1 PID1. Output 2 PID3 dead-band setting screen 2993 Initial value:0.0 0.0 Setting range:  $-50.0 \sim 50.0\%$ key Contents are the same as output 2 PID1 dead-band setting screen. Output 2 PID3 differential-gap setting screen 2923 Initial value:5 5 Setting range: 1~999 digits key Contents is the same with output 1 PID1. Output 2 PID3 minimum limiter setting screen 2013 Initial value:0.0

Output 2 PID3 maximum limiter setting screen 20H3 Initial value:100.0 100.0 Setting range: output limiter lower limit values+0.1~100.0% key Contents is the same with output 1 PID1. Output 2 soft starting time setting screen 250F Initial value:OFF oFF Setting range:OFF, 0.5~120.0 seconds (setting resolution 0.5 second) key Contents is the same with output 1. Output 2 proportional periodic-time setting screen 30-5 Initial value: Contact output 30.0 seconds 300 Voltage pulse output 3.0 seconds key Setting range: 0.5~120.0 seconds (setting resolution 0.5 second) Contents is the same with output 1. Output 2 characteristics setting screen 2RcE Initial value: ${\it d} {\it R}$ - R Setting range: - R. dR ✓ № key Contents is the same with output 1. Return to mode 4 lead screen. (8) Mode 5 screens Mode 5 screens is the setup screens of event option. Not displayed when option is not added. Mode 5 lead screen Red E No setup. Press Im key, it shifts to the first setting screen, event 1 operation-mode setting screen. ENT key Event 1 operation-mode setting screen E 1\_A Initial value:**~~~** Setting range: Chosen from event type character table. 000 MENU key Event type allotted to event 1 is chosen from character table. Event type character table Character Туре Character Type Control loop alarm 2 No allotment c22 non Upper limit absolute value HR SEP Step signal alarm Lower limit absolute value LR P·E Pattern termination signal alarm 50 End Scale over alarm Program termination signal Maximum deviation alarm Нд Hold Hold signal ProC Ld Program signal Minimum deviation alarm Within deviation alarm Гď U\_SL Up slope signal 00 Without deviation alarm 8-SL Down slope siganal CuR RUN signal Gurantee signal -unControl loop alarm 1 💥 Being initialized if measuring range, scaling, and unit are changed. % Deviation alarm is possible to output at the time of RUN+AUTO. In other events, output is always possible. Event 1 differential-gap setting screen E 1\_8 Initial value:5Digits 5 Setting range: 1~999 Digits New Key ON-OFF differential gap of event 1 is set . Not displayed, when the event 1 mode are as follows.non. 50, run. 52P. P\_E.HoLd.ProG.U\_SL.d\_SL. Change in measuring range, scaling, unit, and the event 1 mode make it initialize. Event 1 standby operation setting screen EI\_S off Setting range:: oFF、1、2 MENU key  $\sigma FF$ : No standby operation, I: standby-operation only at the time of a power-on. **2**: Standby-operation in the following cases. ;At the time of power-on. When each alarm's operating point is changed, When deviation alarm's SV is performed.



When RUN/STBY (RST) is switched, When AUTO/MAN is switched. Not displayed, when the event 1 mode are as follows. ; ۲۰۵۰, 5۰٫۰۰۰, 5৮۶٫ P·E、HoLd、ProG、U\_SL、U\_SL. Change in measuring range, scaling, unit, and the event 1 mode make it initialize.

```
Event 1 latching setting screen
E 1_L
                           Initial value:_FF
 oFF
                          Setting range: OFF. Or
       MENU key
       When latching is set as on, once event is output, even if event is OFF state event output
        state is held. Not displayed when event 1 mode is non.
       Being initialized if measuring range, scaling, and unit are changed.
Event 1 output characteristics setting screen
E :_R
                               Initial value: 🗝 👝
   no
                           Setting range:
       we key Output characteristics event 1 is chosen from no: normal open,
                                                       nc: normal closing
          Not displayed when event 1 mode is n_0 n.
        Note: If nc is chosen, relay turns to ON about 1.8 seconds later when power source is
               switched on,and turns to OFF in event output range.
Event 2 mode setting screen
~_~3
                           Initial value:
  LR
                       Setting range: Chosen from event type character table.
       we key Type allotted to event 2 should be chosen from character table.
       Change in measuring range, scaling, unit, and the event 1 mode make it initialize.
Event 2 differential-gap setting screen
62_d
                            Initial value: 5digit
    5
                          Setting range:1~999 digit
        key The same as event 1.
Event 2 standby operation setting screen
                              Initial value: _FF
8-53
                            Setting range: OFF、1、2
 oFF
     []. key The same as event 1.
Event 2 latching setting screen
82_L
                               Initial value:: oFF
 oFF
                            Setting range:: oFF. on
      key The same as event 1.
Event 2 output characteristics setting screen
8-53
                              Initial value:: ~~
                           Setting range:: no.nc
   no
     d. key The same as event 1.
Event 3 mode setting screen
  Notes: Apart from event 1-2, event 3 is displayed when being added as additional option.
 E3_7
                         Initial value:
  LR
                       Setting range: Chosen from event type character table.
         We key Type allotted to event 2 should be chosen from character table.
       Change in measuring range, scaling, unit, and the event 1 mode make it initialize.
Event 3 differential-gap setting screen
 83_8
                                 Initial value: 5 digit
                          Setting range: 1~999 digit
    5
        Mew key The same as event 1.
      \checkmark
Event 3 standby operation setting screen
 83_5
                                Initial value:_FF
 oFF
                            Setting range: OFF 、 1、2
        Here key The same as event 1.
Event 3 latching setting screen
                              E3_L
 oFF
                            Setting range: OFF. OO
      🕬 key The same as event 1.
Event 3 output characteristics setting screen
 E3_R
                                Initial value: n a
```

(9) Mode 6 screens Mode 6 screens is the setup screens of external control input (DI) option. Not displayed when option is not added. DI input is a no-voltage contact or open collector Mode 6 lead screen ñodE 8 Press 🕅 key , it shifts to the first setting screen, DI1 mode setting screen. ENT key In MAC 3D (48x48), when option of CT OUTPUT is added, DI 1<sup>~</sup>DI3 cannot be chosen and not displayed. DI 1 mode setting screen d 1\_ Ā Initial value: Setting range: chosen from DI operation character table 000 MENU key Choose DI operation that is allotted to DI 1 from character table. DI 2 mode setting screen 95° y Initial value: Setting range: chosen from DI operation character table -0-<sup>MENU</sup> key Choose DI operation that is allotted to DI 2 from character table. DI 3 mode setting screen d3\_7 Initial value: Setting range: Chosen from DI operation character table. non MENU key Choose DI operation that is allotted to DI 3 from character table. DI 4 mode setting screen Notes: Apart from DI 1-3, DI 4 is displayed when being added as additional option. Initial value: non Setting range: Chosen from DI operation character table. 000 MENU key Choose DI operation that is allotted to DI 4 from character table. Return to mode 6 lead screen DI operation character table and restrictions concerning DI DI operation character table DI character Operation type Input Contents detection No allotment non With closed DI terminal Execution SV = 1st SV 58 : 2st SV level 582 2nd SV With closed DI terminal Execution SV = 2nd SV level 583 3rd SV With closed DI terminal Execution SV = 3rd SV level 584 4th SV level With closed DI terminal Execution SV = 4th SV control RUN RUN with closed DI terminal, STBY with open one. level runProG Program with closed DI terminal. program level Constant value with opened.

\*When  $5B2 \sim 5BH$  are conducted during AT execution, they are performed at the time of AT termination.

Manual with closed DI terminal,auto with open one.

AT-start with rise edge.

Program's time stops temporarily.

Shift to the next program's step.

Choose pattern 1 with close DI rerminal

Choose pattern 2 with close DI rerminal

Choose pattern 3 with close DI rerminal

Choose pattern 4 with close DI rerminal

All latching are released by rise edg.

Release with opened.

Super keylock with closed DI terminal.

\*When  $5B : \sim 5B H$  are allotted to to each DI, priority is given to I - 2 - 3 - H in order. \*RE can be performed at the time of a RUN-automatic output.

\*When **A** is allotted to, release in the middle of AT operation is carried out by off-key operation chosen in AT screen.

\*While AT is performed, if STBY (RST) or a manual output is performed, AT is released.

level

edge

level

edge

level

level

level

level

edge

level

\*Even when a keylock is not OFF conducting of DI is effective.

Return to mode 5 lead screen

\*The same operation other than non is impossible to allot to DI1-DI4 at a time.
\*Operation allotted to DI takes priority over DL. Key operation cannot be performed.
\*Execution of DI operation is possible to perform. But neither release of AT nor numerical change of SV and manual output is possible to perform.\*In DI input, 5VDC 0.5mA per point is impressed.Use endurable switch, transistor and so on.
•Wiring distance of DI should be less than **30m**.

12

<u> A</u>Rn

RE

Hold

SHEP

PE\_ 1

PE\_2

PE\_3

*Р*Е\_Ч

LL-S

LocY

manual inpu t

auto tuning

Pattern 1

Pattern 2

Pattern 3

Pattern 4

latching release

super key lock

hold

skip

#### (10) Mode 7 screens

The Mode 7 screens is the setup screens of analog output option.

Not displayed when option is not added.

In MAC 3D (48x48),when communication option isadded,it is impossible to choose and display. Mode 7 lead screen

#### ñodE

 When
 Image: key is pressed, it shifts to the first setting screen, analog output mode

 Image: key
 setting screen.

# Analog output mode setting screen

 $\mathcal{R}_{\mathcal{O}_{-}}$  Initial value:  $\mathcal{O}_{\mathcal{O}_{-}}$  (does not output)

  $\mathcal{R}_{\mathcal{O}_{-}}$  Setting range:  $\mathcal{P}\mathcal{B}$  PV

  $\mathcal{R}_{\mathcal{O}_{-}}$  Setting range:  $\mathcal{P}\mathcal{B}$  PV

  $\mathcal{R}_{\mathcal{O}_{-}}$   $\mathcal{S}\mathcal{B}$  execution SV

  $\mathcal{R}_{\mathcal{O}_{-}}\mathcal{L}$  control out put 1

  $\mathcal{O}_{-}\mathcal{L}$   $\mathcal{C}$  control out put 2

  $\mathcal{C}\mathcal{L}$   $\mathcal{C}$  CT OUTPUT 1

  $\mathcal{C}\mathcal{L}$   $\mathcal{C}$  CT OUTPUT 2

  $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{C}\mathcal{L}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{L}\mathcal{L}\mathcal{L}$ 
 $\mathcal{O}_{-}\mathcal{L}\mathcal{L}$   $\mathcal{L}\mathcal{L}$ 
 $\mathcal{L}$   $\mathcal{L}\mathcal{L}$ 
 $\mathcal{L}$   $\mathcal{L}\mathcal{L}$ 
 $\mathcal{L}$   $\mathcal{L}\mathcal{L}$ 
 $\mathcal{L}$   $\mathcal{L}\mathcal{L}$ 
 $\mathcal{L}$   $\mathcal{L}\mathcal{L}$ 
 $\mathcal{L}$   $\mathcal{L}\mathcal{L}$  
 <

# Analog output scaling lower limit value setting screen

RS_L	Initial value: the following table
0	Setting range: the following table

<sup>NENU</sup> key

Lower limit value of range allotted to analog output is set up.

However, AS\_L<AS\_H Lower limit value is given priority

MODE		Setting range	Initial value	
PV	sensor input	within measuring range	measuring range lower limit value scaling lower limit value	
SV	linear input	within scaling range		
OU	JT1,0UT2	0.0~99.9	0.0	
CT	1,CT2	0.0~49.9	0.0	

•

Analog output scaling upper limit value setting screen

 R5\_H
 Initial value: the following table

 IOD
 Setting range: the following table

MENU key

Upper limit value of range allotted to analog output is set up.

However, AS\_L<AS\_H Lower limit value is given priority

MODE		Setting range	Initial value	
PV	sensor input	within measuring range	measuring range upper limit value scaling upper limit value	
SV	linear input	within scaling range		
OUT1	,0UT2	0.1~100.0	100.0	
CT1, C	CT2	0.1~ 50.0	50.0	

Lower limit value takes priority, therefore upper limit value cannot be set below the value of lower limit value +1. When a lower limit value is set more than upper limit value, upper limit value is push to the level of lower limit value +1.

√ Amelan aut

Analog output limiter lower limit value setting screen

RL_L	Initial value: 0.0
0.0	Setting range:0.0~100.0%
MEN	key
	The lower limit value of analog output value (4–20mA) is set up by %.
Fo	or example, output value of a lower limit value in each setup are:8mA(25.0),
	12mA(50.0), 16mA(75.0) and 20mA(100.0 ) respectively.
$\downarrow$	
Analog ou	tput limiter upper limit value setting screen
RL_H	Initial value:100.0
1000	<b>S</b> Setting range: 0.0~100.0%
6	w key
	Upper limit value of analog output value (4–20mA) is set up by %.
$\downarrow$ 1	f set as the same value as $m{R}\climet{L}\cdot m{L}$ and $m{R}\climet{L}\cdot m{H}$ , it is fixed to the value.

Return to mode 7 lead screen

(11) Mode 8 screens Mode 8 screens is the setup screens of CT OUTPUT option. Not displayed when option is not added. In MAC 3D (48x48), when DI 1~3 are added, it is impossible to choose and display. Mode 8 lead screen ñodE 8 Press Im key , it shifts to the first setting screen, CT1 mode setting screen. ENT key C 1\_ A Initial value: Setting range: non.out 1.out2. 000 MENU key ER 1'ER5'ER3 Object detected by CT (current) sensor is chosen. In the case of a current output,  $\mathbf{D} \mathbf{L} \mathbf{L}$  is not displayed. out 2 option. EBI\_2 and 3 are not displayed without any option, respectively. CT1 delay time setting screen C 1\_ A Initial value:0.5 0.5 Setting range:  $0.5 \sim 30.0$  seconds wwwww.when control loop abnormal alarm is allotted to event, delay time from switchover of operation (ON-OFF) to detection start is set up.

CT2 mode setting screen

C2_7	Initial value:
	Setting range:
MENU	key <b>EB1.EB2.EB3</b>
Т	he same as CT1 mode setting screen.
$\checkmark$	
CT2 delay t	ime setting screen
62_Ä	Initial value: 0.5
0.5	Setting range: 0.5~30.0 seconds
	key The same as CT1 delay time setting screen
Return to n	node 8 lead screen

#### About control loop abnormal alarm

When the targeted output of a control loop abnormal alarm is ON, if current detected by CT is lower than the allotted event's operating point(Setting Value of a basic screens, event operating point setting screen)

alarm output is issued as breaking alarm.

When the targeted output is OFF, if detected current is higher than the allotted event's operating point (short-circuit, earth fault, etc.)

#### (12) Mode 9screens

Mode 9screens is the setup screens of communication (RS-485) option. Not displayed when it isnot added. See the attached Communication Instruction Manual (in the appendix : "at the time of communication option added") about communication,

The co. 7 and and og output innicon our bo mado into roveroo oodiing.

Example: Output range :0°C (4mA)~ 1200°C (20mA) can be 0°C (20mA) ~ 1200°C (4mA).

Set AL\_L as 100% and AL\_H as 0.0%.

#### 5-5. measuring rangecode table

				Measurein	g Range		
	Input Type		Code	Unit Code <b>(</b> °C)	Unit Code <i>F</i> (°F)		
		R	- 1	0 ~1700	0 ~3100		
		К	<i>۲</i> :	-199.9~ 400.0	$-300 \sim 700$		
		К	24	0 ~1200	0 ~2200		
		K	<i>24</i>	0.0~ 300.0	$0 \sim 600$		
		К	PЧ	0.0~ 800.0	0 ~1500		
		J	ا لے	$0 \sim 600$	0 ~1100		
		J		0.0~ 600.0	0 ~1100		
	Thermo	T	E /	-199.9~ 200.0	$-300 \sim 400$		
	Couple	E	E :	$0 \sim 700$	0 ~1300		
		S	5:	0 ~1700	0 ~3100		
		*5U	ינ	-199.9~ 200.0	$-300 \sim 400$		
		N		0 ~1300	0 ~2300		
М		*1B	61 57	0 ~1800	0 ~3300		
u		*3Wre5-26	5-26	0 ~2300	0 ~4200		
u 1		*4PLII	PL2	0 ~1300	0 ~2300		
			P:	$-200 \sim 600$	-300 ~1100		
t :			<i>P2</i>	-100.0~ 200.0	-150.0~ 400.0		
i		*6	P3	0.0~ 100.0	0.0~ 200.0		
		*6	РЧ	- 50.0~ 50.0	-60.0~ 120.0		
I			<i>P</i> 5	-100.0~ 300.0	-150.0~ 600.0		
n			<i>P</i> 6	-199.9~ 300.0	-300 ~ 600		
р	Resistance	Bulb Pt100	<i>P</i> 7	-199.9~ 600.0	-300 ~1100		
u			P8	$0 \sim 230$	$0 \sim 450$		
t			JP I	$-200 \sim 500$	$-300 \sim 900$		
		*6		-100.0~ 200.0	-150.0~ 400.0		
		*6	 _JP3	0.0~ 100.0	0.0~ 200.0		
			ੁpਪ .ee	- 50.0~ 50.0	-60.0~ 120.0		
			JPS	-100.0~ 300.0	-150.0~ 600.0		
			JP6	-199.9~ 300.0	$-300 \sim 600$		
			רקנ	-199.9~ 500.0	$-300 \sim 900$		
			JP8	$0 \sim 230$	$0 \sim 450$		
	Volatage(1	mV)*70∼ 10	ā (				
		0~100	57				
		*7-10~ 10	<i>.</i> 73				
		$0\sim 20$	ลิฯ	Scaling Range:-1999~99	99 Digit		
_		$0\sim 50$	<i>.</i> 75	Span:10~10000Digit			
Vol	ltage(V)	1~ 5	8:	Change of decimal point's p	osition is possible		
		0~ 5	82	(no decimal pont,	0.1, 0.01, 0.001)		
		-1~ 1	83	1			
		$0\sim 1$	84	1			
		$0\sim 2$	85	1			
		$0\sim 10$	85	1			
Cu	rent(mA)	$4 \sim 20$		1			
		$0\sim 20$	582	1			
the	mo couple	B,R,S,K,E,J,T,N		1			
	sistance bul						
10		JPt100:513/11					
*1	thermo cou			below B:400°C (752 °F).			
	thermo cou		-	$6FS \text{ for } 0 \sim -100^{\circ}C  (-148)^{\circ}$	°F) and		
. 2	3.0.110 00U		S if it is below—1	_	. , unu		
*3	thermo cou						
*3 thermo couple Wre 5-26: Product of Hoskins Mfg, co., *4 thermo couple PL II : Platinel							
*4 thermo couple PLI: Platinel *5 thermo couple U:DIN43710							
		•		°C, 0.0~100.0°C is ±0.3%FS	2		
	voltage(m		-	~10mV is ±0.3% of input rar			
Set	up of factor	y shipment is N	-	mo couple <i>H2</i> 0-120			
			0 1	$-5V$ $\vec{a}$ ; 0.0-100			
~				4–20mA <b>AR i</b> 0.0–10	0.0		
. Su	ppiementary	Explanation of F	unction				

6. Supplementary Explanation of Function

# 6-1. Auto return function

When there is no key operation 3 minutes or more,on the screen except for basic screen and each monitoring screen, screen automatically shifts to basic screen. (Auto return).

1) Soft- start functions in the following conditions.

 At the time of the power-on in automatic operation, STBY(RST)→RUN, and normal return from scale over.

Scale Over.

-Setup of proportional band (P) is other than  $\mathsf{OFF}$ 

Soft starting time is not OFF

#### 6-3. Event Selection Alarm Operation Figure

The figure of alarm operation figure allotted to event  $1 \sim 3$  is shown.

LA: Lower limit absolute value alarm HR: Upper limit absolute value alarm



 $\Delta$ : SV  $\blacktriangle$ : Alarm operating point setting value

Hd: Upper limit deviation alarm



🗗 🗗 : Without deviation alarm

🗖 🗗 : Within deviation alarm



#### 6-4. AT (Auto Tuning)

 If AT is performed by FIX (constant value control), AT monitor LED blinks and light is put out by termination or intermediate release.

•When auto tuning is ended in inclination step or chosen all PID(s), it is in standby state until one pattern is completed. then lights up, then puts out when one pattern is completed.

•When AT is not completed within 1 pattern, AT conducting is released when one pattern is completed.

•Even in inclination step, AT is performed if it is in HOLD state.

•AT at the time of 2 output specification is as follows.

At the time of heating / cooling operation and cooling / heating operation = OUT1, OUT2 common - PID value

At the time of heating / heating operation and cooling / cooling operation, only OUT1 performs AT.

OUT 2 output while performing AT is 0% or output limiter lower limit value.

#### 6-5. 2 output-characteristics figure

2-output -characteristics is shown in the following figure.  $\odot$  Conditions: P operation, manual reset ( $\overline{n}$  - ) -50.0%

1) OUT 1 RA (heating) •OUT 2 DA (cooling) operation



2) OUT 1RA (heating) • OUT 2 RA (heating)



#### 6-2. Output Soft Start Function

This is the function to increase the control output gradually with set-up time at the time of power-on,

STBY $\rightarrow$ RUN, and normal return from scale over. This is effective for controlling the excessive current to loads, such as a heater.



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output 100%

#### 6--6 PID control methid(Flex PID Method add from Ver 1..2)

MAC3 equipped with flex PID which can be suited SV (target value) change followingness as a disturbance in addition to the usual type SHIMAX PID which can be suited for a few target of a disturbance element (factory sewtting)

This is explainaton a modification method of two types PID method both SHIMAX PID methid and Flex PID method.

(1)Setting of PID method



Press BM key 3 seconds at each setting lead screen from Mode 1 to Mode 9, it move to the screen that can be shoosen both SHIMAX PID or Flex PID.

#### (2) About the factor used for Flex PID.(Add from ver 1. 2\*)

There are a factor f for SV change followingness and a disturbance response factor f and b in addition to the SHIMAX PID method, P (proportional band), I (integration time) and D (derivative time) in flex PID, and it's possible to set from 1 to 3 at PID setting screen of output 1 and 2.

At PID setting screen it can be moved to  $\boldsymbol{R}$  setting screen by pressing  $\overline{\mathbb{M}}$  key for 3 seconds. Move to  $\boldsymbol{b}$  setting screen by pressing  $\overline{\mathbb{M}}$  key, move to  $\boldsymbol{c}$  setting screen by pressing  $\overline{\mathbb{M}}$  key, move to  $\boldsymbol{R}$  setting screen by pressing  $\overline{\mathbb{M}}$  key, move to PID setting screen by pressing  $\overline{\mathbb{M}}$  key 3 seconds at  $\boldsymbol{R}$  setting screen.



(3) Adjustment of each Factor

Auto tuning function calculates standard PID for the turbulence response but best value is not necessarily obtained for all applications.

When the auto tuning function finished, it should be confirmed whether the auto tuning result is excellent by giving turbulence by intention while checking the control result.

The integration limitation coefficient is trimmed  $\mathcal{L}$  as an adjustment of the overshoot and undershoots. When  $\mathcal{L}$  is enlarged, it becomes easy for the overshoot and undershoot to go out though the restoration speed quickens.

E setting range=0.00~1.00
Default Value(Value of Output 1 0.4 as same Output 1 & 2)
(0.8 As Reverse-characteristic Output 1 & 2)

Adjustment of follow for Start up and SV change

The turbulence response and the SV change follow can be individually set by Flexible PID method in MAC3. It already set up the turbulence response, and now set it according to the purpose based on the table below.

R	ь	Control method	Features
1	1	I-PD(Measurements proportion differentiation early type)	For fixation control
1	0	ID-P(Measurements proportionally early type)	The kickback by the SV value change is in
0	1	IP-D(Measurements differentiation early type)	target value follow are a little inferior. For ramp control
0	0	PID(Deflection PID)	For target value follow valuing and cascade re
R	0	P-I-PD(P2 flexi type)	Turbulence response and target value follow

*R***b** setting range=0. 00~1. 00 (**PRG**: *R*=0. 20 **b**=0. 20 ) Default value (FIX:  $\mathbf{R} = 0.40 \mathbf{b} = 1.00$ )

 $\boldsymbol{R}$  should be reduced when you want to improve the step response at the SV change and the start-up,  $\boldsymbol{R}$  should be expanded when you wants to reduce the overshoot at the step responds and to reduce the output change.

**b** should be reduced when you want to improve the follow performance at the lamp control, **b** should be expanded When you wants to reduce the overshoot at the lamp ends and to reduce the output change

#### 7. Touble Shooting

#### 7-1. Cause and Treatment of Main Defects

Contents of defects	Cause	Treatment	
Error message display	Refer to cause and treatment of	Refer to cause and treatment of error	
	error	display	
	display		
PV display is not normal	Mismatch of instrument and input.	Type code, check of specification.	
	Fault in the wiring.	Check of wiring.	
Display disappeared and	Power is not supplied.	Check of a power supply (voltage of	
does not operate	Abnormality of instrument.	terminal, switch, fuse, wiring).	
Key operation impossible	Keylocked.	Release of keylock.	
	Abnormality of instrument.	Check of instrument, repair, exchange.	

## 7-2. Cause and Treatment of Error Display

(1) Abnormality Display of Measurement Input

Error display	Contents	Cause	Treatment	
нннн	Scale over in upper limit	1.wire breaking of thermocouple input	1.wire breaking check of thermocouple input wiring,	
(HHHH)		2.wire breaking of resistance bulb input A	replacement of thermocouple	
		3.when input exceeds upper limit of measuring range b	y 10% 2.check of resistance bulbA wiring, replacement of	
			resistance bulb	
			3.check of input voltage value and current value, input	
			transmitter and specification (matching of incoming	
			signal and meter specification)	
LLLL	Scale over in lower limit	1.when input exceeds lower limit of measuring range b	y 10% 1.polarity of input is everse, check of wiring and an input	
(LLLL)		2.wire breaking of resistance bulb input B*	transmitter	
			2.check of resistance bulb B wiring, replacement of	
			resistance bulb	
		*B: Wiring of MAC3A, 3B's terminal No.11, Wiring of MAC 3D's terminal No.5		
6	Breaking of resistance bulb input	1.wire breaking of b*	1.check of resistance bulb wiring	
(B)		*b: Wiring of MAC 3A, 3B's terminal No.12, wiring of MAC 3D's terminal No.6		
		2.multiple wire breaking combinations in Abb	2.replacement of resistance bulb	
		(A and B, A and b, B and b, all of ABB)		
С ЈНН	Cold junction (CJ) temperature of thermocouple	When ambient temperature of a meter exceeds 80°C	1.make Ambient temperature of meter within use environment	
(CJHH)	input is scale over in upper limit side		condition temperature	
			2. Check the meter when ambient temperature is not over $80^\circ C$	
C JLL	Cold junction (CJ) temperature of thermocouple	When ambient temperature of meter becomes less	1.make Ambient temperature of meter within use environment	
(CJLL)	input is scale over in lower limit side	than —20°C	condition temperature	
			2. Check the meter when ambient temperature is not less than	
			-20°C	

# 8. Specification

Display

Display							
Display method	Digital display:	MAC3A (96 x 96 size)	PV red 7	segment LED	4 figure (height of character about 20mm)		
			SV green 7	segment LED	4 figure (character quantity about 13mm)		
		MAC3B(48x96 size)	PV red 7 se	gment LED	4 figure (height of character about 12mm)		
			SV green 7	segment LED	4 figures (height of character about 9 mm)		
		MAC3C(72 x72 size)	PV red 7	segment LED	4 figure (height of character about 16mm)		
			SV green 7	segment LED	4 figures (height of character about 16 mm)		
		MAC3D (48x48 size)	PV red 7 se	egment LED	4 figure (height of character about 12mm)		
			SV green 7	segment LED	4 figures (height of character about 9mm)		
		Status display: RUN	(green), PRO	G (green), AT (g	reen), OUT 1(green)		
		EV1 (yellow), EV2 (yell	ow), OUT2 /	EV3 (yellow)			
Display accura	су	: $\pm$ (0.25%FS+1digit)CJ e	rrors not inc	luded, B thermo	o couple below 400°C is not guaranteed.		
		Display accuracy durin	g EMC exam	ination is $\pm 5\%$ F	-S.		
Accuracy mainte	nance range :	23±5°C					
Display range	:	-10%-110% of measuring	range, but P	't100's -200~60	0°C is −240~680°C		
Display resolut	ion	: Changes with measurin	ig range and	scaling.			
Input scaling		: Possible at the time of voltage input and current input $-1999-9999$ (spang 10 $-$ 10000 count, decimal point position					
		no decimal point 0.1, 0	.01, 0.001)				
Setting							
Setting system	I	: By five front keys ( 🖻	u 🔻 🔺 ent,run	).			
SVSetting range		: Same with measuring r	ange				
Setting lock		: Communication and ke	ey seting (thr	ee levels), DI (o	ne level)		
		Operations	Level	Lock Content			
		Communication	OFF	No lock			
		&	1	Execution SV	and a manual numerical change are possible. And change of a keylock level is possible.		
		Key setting	2	Possible to cl	hange numerical value manually and keylock level.		
			3	Possible to cl	hange keylock level.		
			4	Only change	of a keylock is possible It can be locked 🔤 key		
		DI Setting	Super K	ev Lock (Shift b	between screens prohibited. Fixed only to the basic screen.)		
		* Regardless of the setting lock by communication & key setting, the Rem key is always effective.					
		-			er keylock by DI is performed.		
SV setting limiter	: Sa	me with measuring range	( lower limit	< upper limit	)		
Unit setting		ttable at the time of sens		••			
Input							
Multi input							
Thermocoup	le :	500 $\Omega$ or more, external (	resistance to	lerance level	100 $\Omega$ or less input resistance		

Influence of lead-wire	:1.2 μ V ∕ 10 Ω
Burnout	:Standard equipment (Up Scale only)
Measuring range	:Item 5-5. Refer to measuring range code table.
Compensation accuracy	
of reference junction	: $\pm$ 1 °C (ambient temperature 18-28°C) At the time of vertical plural proximity attachment $\pm$ 2°C
	$\pm 2^{\circ}$ C (ambient temperature 0-50°C) At the time of vertical plural proximity attachment $\pm 3^{\circ}$ C
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Tracking of a reference	
junction :	:Below the ambient temperature of 0.5 $^\circ \! C$ / min, compensation accuracy of reference junction $\pm1^\circ \! C$
Resistance bulb stipulated	
current resistance bulb	: Approx. 0.25mA
Lead wire resistance	
tolerance level	:5 $\Omega$ or less per wire (Resistance of three lines should be equal)
Influence of lead-wire	
resistance :5	$5\Omega$ or less per wire 0.2%FS
10	$\Omega\Omega$ or less per wire 0.5%FS
20	$0\Omega$ or less per wire 1.0%FS
Measuring range	:Item 5-5. Refer to measuring range code table.
Voltage (mV) Input resistor	:500k $\Omega$ or more
Input voltage range	:Item 5-5. Refer to measuring range code table.
Voltage input (V) Input resist	tor:500kΩ or more
Input voltage range	:Item 5-5. Refer to measuring range code table.
Current input (mA) reception	
Resistance	:250 $\Omega$ (built-in)
	:Item 5–5. Refer to measuring range code table.
Sampling period	
	: 0.25 second
PV filter	:0 - 9999 second
PV offset compensation	: ± 500 unit
PV gain correction	:±5.00%PV filter
Control	
Control system	: PID control with an auto tuning function or ON-OFF operation
Proportional band (P)	: OFF and 0.1 - 999.9% of measuring range (ON-OFF operation by OFF setting)
ON-OFF Differential-gap (DF)	: 1 – 999 unit
Integration Time (I)	: OFF, 1- 6000 seconds (PD operation by OFF setting) If both I and D are OFF, P operation.
Manual Reset (MR)	: $\pm$ 50.0% (effective when set as I = OFF)
Output 2 dead band	: -1999 - 5000 unit
Output limiter (OL, OH)	:0.0 - 100.0% (OL <oh) (set="" 0.1)<="" resolution="" td=""></oh)>
Soft start	: OFF, 0.5 – 120.0 seconds (set resolution 0.5)
Proportional period	:0.5 – 120.0 seconds (set resolution 0.5)
Proportional period Control output characteristic	:0.5 - 120.0 seconds (set resolution 0.5) :Output 1. output 2. Possible to choose either RA (heating) or DA (cooling).
Control output characteristic	: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).
Control output characteristic Manual output	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1)
Control output characteristic Manual output	: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).
Control output characteristic Manual output	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1)
Control output characteristic Manual output * Each parame	: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). : 0.0 - 100.0% (set resolution 0.1)
Control output characteristic Manual output * Each parame Control output 1	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.
Control output characteristic Manual output * Each parame Control output 1 Contact	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load)
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive)	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive)	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive)	: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current	<ul> <li>:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>:0.0 - 100.0% (set resolution 0.1)</li> <li>eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option)	<ul> <li>: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>:0.0 - 100.0% (set resolution 0.1)</li> <li>eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>: normal open (1a) 240V AC 2A (resistance load)</li> <li>: 12V DC+1.01.5V MAX20mA</li> <li>: 4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> <li>: Control out put 2 is exclusive option of event 3 and DI4.</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact	<ul> <li>: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>:0.0 - 100.0% (set resolution 0.1)</li> <li>eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>: normal open (1a) 240V AC 2A (resistance load)</li> <li>: 12V DC+1.01.5V MAX20mA</li> <li>: 4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> <li>: Control out put 2 is exclusive option of event 3 and DI4.</li> <li>: normal open (1a) 240V AC 2A (resistance load)</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive)	: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 :Control out put 2 is exclusive option of event 3 and DI4. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive)	: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter;( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 :Control out put 2 is exclusive option of event 3 and DI4. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less ,display accuracy±1% (accuracy maintenance range 23°C±5°C )
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive)	<ul> <li>:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>:0.0 - 100.0% (set resolution 0.1)</li> <li>eter.(P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.0—1.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> <li>:Control out put 2 is exclusive option of event 3 and DI4.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.0—1.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less , display accuracy±1% (accuracy maintenance range 23°C±5°C )</li> <li>Load regulation ±0.2%, resolution approx. 1/200</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current	<ul> <li>:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>:0.0 - 100.0% (set resolution 0.1)</li> <li>eter.(P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.0—1.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> <li>:Control out put 2 is exclusive option of event 3 and DI4.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.0—1.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less , display accuracy±1% (accuracy maintenance range 23°C±5°C )</li> <li>Load regulation ±0.2%, resolution approx. 1/200</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f	<ul> <li>: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>::0.0 - 100.0% (set resolution 0.1)</li> <li>ater,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>: normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> <li>: Control out put 2 is exclusive option of event 3 and DI4.</li> <li>: normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less , display accuracy±1% (accuracy maintenance range 23°C±5°C )</li> <li>Load regulation ±0.2%, resolution approx. 1/200</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern	<ul> <li>: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>::0.0 - 100.0% (set resolution 0.1)</li> <li>ater,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>: normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> <li>: Control out put 2 is exclusive option of event 3 and DI4.</li> <li>: normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less , display accuracy±1% (accuracy maintenance range 23°C±5°C )</li> <li>Load regulation ±0.2%, resolution approx. 1/200</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps	<ul> <li>:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>:0.0 - 100.0% (set resolution 0.1)</li> <li>ater,( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> <li>:Control out put 2 is exclusive option of event 3 and DI4.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500 Ω or less , display accuracy±1% (accuracy maintenance range 23°C±5°C )</li> <li>Load regulation ±0.2%, resolution approx. 1/200</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter.( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 : Control out put 2 is exclusive option of event 3 and DI4. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less ,display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/200 fuinction add from Ver 1.3*) : Choosen from pattern 1,2,4 Add from Ver 1.3* :Maximum 40steps When choose pattern 1,20steps of each steps when choose pattern 2,10steps of each steps when choose patter : Each output has three kinds. PID1, PID2, and PID3.
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection Time setting	<ul> <li>:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling).</li> <li>:0.0 - 100.0% (set resolution 0.1)</li> <li>ster.(P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C)</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> <li>:Control out put 2 is exclusive option of event 3 and DI4.</li> <li>:normal open (1a) 240V AC 2A (resistance load)</li> <li>:12V DC+1.01.5V MAX20mA</li> <li>:4 - 20mA DC load resistance 500Ω or less ,display accuracy±1% (accuracy maintenance range 23°C±5°C )</li> <li>Load regulation ±0.2%, resolution approx. 1/12000</li> </ul>
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection Time setting Time setup resolution Time accuracy	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :0.0 - 100.0% (set resolution 0.1) eter.( P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 : Control out put 2 is exclusive option of event 3 and DI4. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less , display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/1200 function add from Ver 1.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less , display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/200 function add from Ver 1.3*) : Choosen from pattern 1.2.4 Add from Ver 1.3* :Maximum 40steps When choose pattern 1.20steps of each steps when choose pattern 2,10steps of each steps when choose patter :Each output has three kinds. PID1, PID2, and PID3. :0 minute 0 second~99 minutes 59 seconds or 0 hour 0 minute~99 hours 59 minutes or 0.0 - 999.9 hours ,and ∞ (infinity) :1 second or 1 minute or 0.1 hour
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection Time setting Time setup resolution Time accuracy In a step Setting parameter	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :00 - 100.0% (set resolution 0.1) ster.(P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) : 12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 : Control out put 2 is exclusive option of event 3 and DI4. :normal open (1a) 240V AC 2A (resistance load) : 12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less ,display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/200 function add from Ver 1.3*) : Choosen from pattern 1.2.4 Add from Ver 1.3* : Maximum 40steps When choose pattern 1.20steps of each steps when choose pattern 2,10steps of each steps when choose patter :Each output has three kinds. PID1, PID2, and PID3. : 0 minute 0 second~99 minutes 59 seconds or 0 hour 0 minute~99 hours 59 minutes or 0.0 - 999.9 hours ,and ∞ (infinity) :1 second or 1 minute or 0.1 hour :± (Setup time × 0.005 +0.25 second) :SV, time, PIDNa.
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection Time setting Time setup resolution Time accuracy In a step Setting parameter Number of repeats	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :00 - 100.0% (set resolution 0.1) ster.(P, 1, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 :Control out put 2 is exclusive option of event 3 and D14. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less ,display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/200 function add from Ver 1.3*) :Choosen from pattern 1.2.4 Add from Ver 1.3* :Maximum 40steps When choose pattern 1.20steps of each steps when choose pattern 2,10steps of each steps when choose patter Each output has three kinds. PID1, PID2, and PID3. :0 minute 0 second~99 minutes 59 seconds or 0 hour 0 minute~99 hours 59 minutes or 0.0 - 999.9 hours ,and ∞ (infinity) :1 second or 1 minute or 0.1 hour :± (Setup time × 0.005 +0.25 second) :SV, time, PIDNa. :1 - 9999 times, and ∞
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection Time setting Time setting Time setting Time setting parameter Number of repeats Time signal	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :00 - 100.0% (set resolution 0.1) tetr.(P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.0—1.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 :Control out put 2 is exclusive option of event 3 and DI4. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.0—1.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less ,display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/12000 function add from Ver 1.3* :Choosen from pattern 1.2,4 Add from Ver 1.3* :Maximum 40steps When choose pattern 1.20teps of each steps when choose pattern 2.10steps of o.0 – 999.9 hours ,and ∞ (infinity) :1 second or 1 minute or 0.1 hour :± (Setup time × 0.005 +0.25 second) :SV, time, PIDNk. :1 - 9999 times, and ∞ :Possible to allot to Event (1 second for changeover, 3 seconds for patter end, 3 seconds for program end)
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection Time setting Time setup resolution Time accuracy In a step Setting parameter Number of repeats Time signal PV start function	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :00 - 100.0% (set resolution 0.1) tetr.( P. I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.0—1.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 :Control out put 2 is exclusive option of event 3 and D14. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.0—1.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/2000 function add from Ver 1.3*) : Choosen from pattern 1.2.4 Add from Ver 1.3* :Maximum 40steps When choose pattern 1.20steps of each steps when choose pattern 2,10steps of each steps when choose pattern 1,20steps 10 minute 0 second~99 minutes 59 seconds or 0 hour 0 minute~99 hours 59 minutes or 0.0 – 999.9 hours ,and ∞ (infinity) :1 second or 1 minute or 0.1 hour :± (Setup time × 0.005+0.25 second) :SV, time, PIDMa :1 – 9999 times, and ∞ :Possible to allot to Event (1 second for changeover, 3 seconds for patter end, 3 seconds for program end) :With
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection Time setting Time setup resolution Time accuracy In a step Setting parameter Number of repeats Time signal PV start function Guarantee soak function	: Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :00 - 100.0% (set resolution 0.1) tetr.(P, I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 : Control out put 2 is exclusive option of event 3 and DI4. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.01.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less, display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/1200 function add from Ver 1.3*) : Choosen from pattern 1.2.4 Add from Ver 1.3* : Maximum 40steps When choose pattern 1.20steps of each steps when choose pattern 2,10steps of each steps when choose patter :Each output has three kinds. PID1, PID2, and PID3. : 0 minute 0 second~99 minutes 59 seconds or 0 hour 0 minute~99 hours 59 minutes or 0.0 - 999.9 hours, and ∞ (infinity) :1 second or 1 minute or 0.1 hour :± (Setup time × 0.005 +0.25 second) :SV, time, PIDN& :1 - 9999 times, and ∞ :Possible to allot to Event (1 second for changeover, 3 seconds for patter end, 3 seconds for program end) :With :With Off or 1-2000unit(add from Ver 1. 2*)
Control output characteristic Manual output * Each parame Control output 1 Contact Voltage pulse (SSR drive) Current Control out put 2 (option) Contact Voltage pulse (SSR drive) Current Program function (option)(40step f Number of pattern Number of steps PID selection Time setting Time setup resolution Time accuracy In a step Setting parameter Number of repeats Time signal PV start function	:Output 1, output 2. Possible to choose either RA (heating) or DA (cooling). :00 - 100.0% (set resolution 0.1) ter.( P. I, D, DF, MR, OL, and OH) of Outputs 1 and Outputs 2, Flex PID belongs to 1~3 categories. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.0—1.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less Display accuracyaccuracy±1% (accuracy maintenance range 23°C±5°C) Load regulation ±0.2%, resolution approx. 1/12000 :Control out put 2 is exclusive option of event 3 and D14. :normal open (1a) 240V AC 2A (resistance load) :12V DC+1.0—1.5V MAX20mA :4 - 20mA DC load resistance 500 Ω or less ,display accuracy±1% (accuracy maintenance range 23°C±5°C ) Load regulation ±0.2%, resolution approx. 1/200 function add from Ver 1.3*) : Choosen from pattern 1.2.4 Add from Ver 1.3* :Maximum 40steps When choose pattern 1.20steps of each steps when choose pattern 2,10steps of each steps when choose patter Each output has three kinds. PID1, PID2, and PID3. :0 minute 0 second~99 minutes 59 seconds or 0 hour 0 minute~99 hours 59 minutes or 0.0 – 999.9 hours ,and ∞ (infinity) :1 second or 1 minute or 0.1 hour :± (Setup time × 0.005+1.25 second) :SV, time, PIDMA :1 - 9999 times, and ∞ :Possible to allot to Event (1 second for changeover, 3 seconds for patter end, 3 seconds for program end) :With

Several minutes after power-on, accuracy is not guaranteed. Reaches the accuracy level within 5 minutes after power-on.



Event 1.2 (option)

:2 sets

Output rating Kind of event

: Contact Normal open (1a) 240V AC 2A (resistance load) EV1•EV2 and common :Refer to following table.

	5					
	Function		Characte	r Note		
	No allotment					
	Upper limit absol	ute value Alarm	HR			
	Lower limit absol		LR			
	Scale over alarm		Sa		Jayed.	
	Upper limit devia	tion value Alarm	НВ			
	Lower limit devia		Ld			
	Within deviation a		 Cd			
	Without deviation		00			
	RUN signal		- UC			
	Control loop alar	m				
	(Heater breaking				-	
		/ 1000/	<u> </u>		-	
	Step signal		552			
	Pattern end signa		P_8		rn end	
	Program end sign	าลเ	<u> </u>			
	Hold signal		Hold			
	Program signal		<u> </u>			
	Upslope signal		0_56			
	Downslope signal		8-56		_	
	Guarantee signal		608	Operates when approaches the targeted va	alue exceeding the EV value.	
Standby operation	: OFF No standby operation 1 Only at the Time of Power-on, standby operation					
Standby operation	Control loop alarm 0.0–50.0A					
	1 Only at the Time of Power-on, standby operation					
	2 At the Time of pow	er switch on, each a	alarm operatir	ng point is changed, deviation alarm's execution S	SV is changed,	
	and RUN/STBY	(RST) is switched o	over standby	operation, at the time of AUTO/MAN switchover		
atching	: Alarm operation main	tenance function(Re	elease is done	e by key operation, DI, or power OFF.		
		ase by DI and power	<sup>-</sup> OFF, all alar	ms are called off simultaneously)		
Differential gap	: 1 – 999 unit					
Output characteristic	: Choose from normal	-	-			
		-	-	es ON about 1.8 seconds and becomes OFF at e	vent power range.	
Event3 (Option)		ve selection option o		put 2 and DI4.		
DI 1_9_2 (+:- )	: Item and contents a			with CT is suit		
DI 1-2-3 (option)		AC 3D, exclusive sele	ection option	with GT input.		
Input rating	: 5V DC 0.5mA	abla				
Allotment function	: Refer to following t		Incut	Contento	7	
	DI	Operation type	Input	Contents		
	character	Na allatara d	detection		=	
		No allotment	1		-	
	582	2nd SV	level	With closed DI terminal Execution SV = 2nd SV		
	583	3rd SV	level	With closed DI terminal Execution SV = 3rd	1	
	584	4th SV	level	SV With closed DI terminal Execution SV = 4th	-	
				SV		
	- Un	control RUN	level	RUN with closed DI terminal, STBY with open		
				one.		
	Pro5	program	level	Program with closed DI terminal.	7	
				Constant value with opened.		
	-0	and the second	Law and	Menuel with a leased DI terminal system (1)	7	

-c_5	Pattern 3	level	Choose pattern 3 with close DI rerminal			
РЕ_Ч	Pattern 4 level		Choose pattern 4 with close DI rerminal			
L_~S	latching release	edge	All latching are released by rise edg.			
LocY	LocH super key lock le		Super keylock with closed DI terminal.			
			Release with opened.			

one.

AT-start with rise edge.

Program's time stops temporarily.

Shift to the next program's step.

Choose pattern 1 with close DI rerminal

Choose pattern 2 with close DI rerminal

ā8n

RE

Hold

SHEP

PE\_ 1

PE\_2

manual inpu t

auto tuning

hold

skip

Pattern 1

Pattern 2

level

edge

level

edge

level

level

18

Manual with closed DI terminal,auto with open

jupit of exercision         is Non-voltage contact or open collector           DAI (optic)         is DH is acclusive selection optic outpit active accelusive selection optic for MAC 3D.           Communication function form         is Bit active communication instructions manual that detailed about communication function.           Communication function form         is Bit active communication instructions manual that detailed about communication function.           Communication system         is Avandard RS-485           Marker System         is Avandard RS-485           Communication system         is Avandard RS-485           Marker System         is Avandard RS-485           Communication system         is Avandard RS-485           Marker System <t< th=""><th>Input minimum retention time</th><th>: 0.25 second</th></t<>	Input minimum retention time	: 0.25 second
Number of input::Number of input:::Communication function/combo:::Communication function/combo:::Communication function/combo:::Sommunication system:::Synchronus system:::Communication system:::Synchronus system:::Communication System:::Silve address:::Silve address:::Communication System:::Communication System:::Communication System:::Dispone::::Dispone::::Dispone::::Dispone::::Dispone::::Dispone::::Dispone: <t< td=""><td>Input of operation</td><td>: Non-voltage contact or open collector</td></t<>	Input of operation	: Non-voltage contact or open collector
Number of input::Number of input:::Communication function/combo:::Communication function/combo:::Communication function/combo:::Sommunication system:::Synchronus system:::Communication system:::Synchronus system:::Communication System:::Silve address:::Silve address:::Communication System:::Communication System:::Communication System:::Dispone::::Dispone::::Dispone::::Dispone::::Dispone::::Dispone::::Dispone: <t< td=""><td>DI4 (option)</td><td>: DI4 is exclusive selection option with control output 2, Event3</td></t<>	DI4 (option)	: DI4 is exclusive selection option with control output 2, Event3
Communication function/option       ::::::::::::::::::::::::::::::::::::	Number of input	
Read attached communication instructions manual that detailed about communication function.         Communication system       EX attached communication (RS-485)         Communication system       A synchronous system         Communication function       I 2002 (400, 4000, 9500) (2000 or 38400brs)         Communication function       I 2002 (400, 4000, 9500) (2000 or 38400brs)         Communication function       I 2002 (400, 4000, 9500) (2000 or 38400brs)         Data format       I 2002 (400, 9500) (2000 or 38400brs)         Master function       I 2002 (400, 9500) (2000 or 38400brs)         When MACG is a master, siew address maximum 31)       When MACG is a master, siew address maximum 31)         When MACG is a master, bus connection with other hoat PCs is not allowed.       When MACG is a master, siew address maximum 31)         Slave address       I -255         Parameter preservator       When MACG is a master, bus connection with other hoat PCs is not allowed.         Five ontol       I -000         Communication coad       Slave address         Communication coad       Slave address contravio         Read stachter preservator       When MACG is a master, bus connection with other hoat PCs is not allowed.         Fiver dataction       I -0000s (resolution lms)         Communication coad       Slave address contravio Coad         Imministion resistam       <		: Item and contents are same with DI 1, DI 2 and DI 3.
Communicative topsEIA standardRS-485Communication system:: Worvvire system Naf daplex multi-drops (bus) systemCommunication distance:: Maximum 500m (dependeon conditions)Communication distance:: Start 1bt Stop 1 2 bits Daving and the system numberMaster function:: Start 1bt Stop 1 2 bits Daving and daving system numberMaster function:: Start 1bt Stop 1 2 bits Daving and daving system numberMaster function:: Start 1bt Stop 1 2 bits Daving and daving system numberMaster function:: Start 1bt Stop 1 2 bits Daving and daving system numberMaster function:: Start 1bt Stop 1 2 bits Daving and daving system numberMaster function:: Start 1bt Stop 1 2 bits Daving and daving system numberMaster function:: Start 1bt Stop 1 2 bits Daving and daving system numberMaster function:: Start 1bt Stop 1 2 bits Daving and daving system numberParameter preservative:: None Grow Start machine and slave machine should be equal, at the time of cascade controlBlave address:: I noneParameter preservative:: None Grow Grow ADD, complement of ADD +2, exclusive OR, CRC-18 and LRCFor ordectorin:: Start 1bt Start and connectionIt mutch connection:: Start 1bt Start and connectionIt mutch connection:: Start 1bt Start and connectionOutput kind:: Start 1bt Start and connectionOutput kind:: None Grow Start and connectionOutput ki	Communication function(option)	: Output and an exclusive selection option for MAC 3D.
Communication water is two-wire system half duplex multi-drops (bus) system Synchro system is Maximum 500m (dependence on ditions) Communication states is 1200, 2000, 9000, 9900, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 2120, 2000, 4000, 9000, 1920 or 38400bps Data format is 21-255 Parameter preservation mode: 1-255 Parameter preservation mode: 1-250 Delay 2000 Conse from PAV, SV, OUTI, OUT2, OT1, and CT2. Output kind 2-24-200A DC 300Q or less, Display accuracy maintenance range 25°C±5°C ) Lead regulation±0.058, Resolution approx 1/3000 Parameter preservation ± 100 S (reverse setting is possible) Parameter preservation mode: 1-257 Detection method 2-2050A Sampling period 2-2050A Sampling period 2-257 Detection approx 1-2500 Sacands Alarm output 4-2053 Sacands Alarm output 4-2054 Sacands to OUT1, OUT2, EV1, EV2, and EV3. Alarm output 4-2054 Sacands to OUT1, OUT2, EV1, EV2, and EV3. Alarm output 4-2054 Sacands to OUT1, OUT2, EV1,		Read attached communication instructions manual that detailed about communication function.
Synchro system:Asynchronous systemCommunication distance:Maximum S00m (dependence conditions)Communication Speed:1200, 2400, 4800, 19200 or 38400bpsData format:Start 1bit, Stop 1, 2 bits, Data length 7 or 8 bits, Parity without, odd number, even numberMaster function:Chooses from SV, OUTI, OUT2 (Im, number of slaves maximum 31)When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuation. : %When MAC3 is a master, slave address range must be continuet. : 1 = 500 file (Solution 1ms)Communication resistance:: noreProtocol:: StilfMAX Standard or MODBUS AGL MODBUS RTU protocolTermination resista	Communicative type	: EIA standard RS-485
Communication distance: Maximum 500m (dependson conditions)Communication Speed:: Start bit, Stop 1 2 bits, Data length 7 or 8 bits, Parity without, odd number, even numberMaster function:: Chooses from SV, OUT1, OUT2 (1n number of slaves maximum 31) .: When MAG3 is a master, slave address range must be continuation. .: Without Ango is a master, slave address range must be continuation. .: Without Ango is a master, slave address range must be continuation. .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalat the time of cascade control .: Without range of master machine and slave machine should be equalated the time of cascade control .: None-Control .: Invertee transe of master machine and slave machine should be equalated the time of cascade control .: Invertee transe of master machine and slave machine should be equalated the time of cascade control .: None-Control .: Invertee transe of master machine and slave machine should be equalated the time of cascade control .: Invertee transe of master machine should be equalated the time of cascade control .: Inver	Communication system	: Two-wire system half duplex multi-drops (bus) system
Communication Speed:Data format:Start 1bit, Stop 12 bits, Data length 7 or 8 bits, Parity without, odd number, even numberMaster function::Chooses from SV, OUTI, OUT2 (1n: number of slaves maximum 31):::::::::::::::::::::::::::::::::::	Synchro system	: Asynchronous system
Data format:Start 1bit, Stop 12 bits, Data length 7 or 8 bits, Parity without, odd number, even numberMaster function:Chooses from SV, OUTI, OUT2 (In number of slaves maximum 31) : : When MAC3 is a master, slave address range must be continuation. : When MAC3 is a master, bus connection with other host PCs is not allowed. : : Brametter preservation mode: : Noose from RAM, MIX and EEP mode.Parametter preservation mode: Information control: : : None. Choose from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRCFlow control: : 	Communication distance	: Maximum 500m (dependson conditions)
Master function       : Chooses from SV. OUT1, OUT2 (1:n number of slaves maximum 31)         ※ When MAC3 is a master, slave address range must be continuation.         ※ When MAC3 is a master, slave address range must be continuation.         ※ When MAC3 is a master, slave address range must be continuation.         ※ When MAC3 is a master, slave address range must be continuation.         ※ When MAC3 is a master, slave address range must be continuation.         ※ When MAC3 is a master, slave address range must be continuation.         ※ When MAC3 is a master, slave address range must be continuation.         Stave address       : 1-255         Parameter preservation mode:       Chooses from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRC         Flow control       : none         Delay       : 1 - 500ms (resolution 1ms)         Communication code       : ASCII code or binary code         Protocol       : SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Terministion resistance       : 120 Q (external connection)         Number of connection       : Maximum 32 sets (depends on conditions, host is included)         Analog output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : 4 - 20mA DC 300Q or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C )         Load regulation ±0.05%, Resolution approx 1/50.000         Scaling fun	Communication Speed	: 1200, 2400, 4800, 9600, 19200 or 38400bps
** When MAC3 is a master, slave address range must be continuation.         ** Unput range of master machine and slave machine should be equal at the time of cascade control         ** Input range of master machine and slave machine should be equal at the time of cascade control         ** Input range of master machine and slave machine should be equal at the time of cascade control         ** Input range of master machine and slave machine should be equal at the time of cascade control         ** Input range of master machine and slave machine should be equal at the time of cascade control         ** For detection       * None, Choose from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRC         For detection       * None, Choose from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRC         For detection       * Insc.         Communication code       * ASCII code or binary code         Protocol       * SIMMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       * 1200 (certernal connection)         Number of connection       * Maximum 32 sets (depends on conditions, host is included)         Output kind       * Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output traing       * 4-20mA DG 300 QO reless, Display accuracy maintenance range 23°C±5°C )         Lad regulation ±0.05%, Resolution approx 1/50.000       * analog output upper limit value < analog output upper limit value	Data format	: Start 1bit, Stop 1 2 bits, Data length 7 or 8 bits, Parity without, odd number, even number
**       When MAC3 is a master, bus connection with other host PCs is not allowed.         **       Input range of master machine and slave machine should be equal at the time of cascade control         **       Input range of master machine and slave machine should be equal at the time of cascade control         **       Parameter preservator         **       Flow control       :         **       None, Choose from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRC         Flow control       :       in one         Delay       :       1 - 500m (resolution 1ms)         communication code       :       SKIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       :       120.02 (external connection)         Number of connection       :       Maximum 32 sets (depends on conditions, host is included)         Analog output(AO)       :       In MAC 3D, exclusive selection option with communication function         Output kind       :       :       Choose from PV, SV, OUTI, OUTZ, CTI, and CT2.         Output kind       :       :       :       :         Output limiter       :       :       :       :         Output limiter       :       :       :       :         Detection method       :       :       :       :	Master function	: Chooses from SV, OUT1, OUT2 (1:n number of slaves maximum 31)
We have range of master machine and slave machine should be equal, at the time of cascade control         Slave address       : 1-255         Parameter preservation mote:       : Choose from RAM, MIX and EEP mode.         Error detection       : None, Choose from RAD, complement of ADD +2, exclusive OR, CRO-16 and LRC         Flow control       : one         Delay       : 1 - 500ms (resolution 1ms)         Communication code       : ASCII code or binary code         Protocol       : SHMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       : 1200 (external connection)         Number of connection       : Maximum 32 sets (depends on conditions, host is included)         Output kind       : Ohoose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output kind       : Ohoose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output limiter       : with (range depends on output type) analog output lower limit value < analog output upper limit value		※ When MAC3 is a master, slave address range must be continuation.
Slave address       : 1-255         Parameter preservation mode:       Choose from RAM, MIX and EEP mode.         Error detection       : None, Choose from RAD, complement of ADD +2, exclusive OR, CRC-16 and LRC         Flow control       : none         Delay       : 1 - 500ms (resolution 1ms)         Communication code       : ASCII code or binary code         Protocol       : SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       : I 20 Ω (external connection)         Number of connection       : Maximum 32 ests (depends on conditions, host is included)         Analog output(AO)       : In MAC 3D, exclusive selection option with communication function         Output kind       : Ohoose from PV, SV, OUTI, OUT2, CT1, and CT2.         Output kind       : Ohoose from PV, SV, OUTI, OUT2, CT1, and CT2.         Output kind       : with (range depends on output type) analog output lower limit value < analog output upper limit value		※ When MAC3 is a master, bus connection with other host PCs is not allowed.
Parameter preservation mode:       Choose from RAM, MIX and EEP mode.         Error detection       : None, Choose from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRC         Flow control       : none         Delay       : 1 - 500ms (resolution 1ms)         Communication code       : ASCII code or binary code         Protocol       : SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       : 120Q (external connection)         Number of connection       : Maximum 32 sets (depends on conditions, host is included)         Analog output(AO)       : In MAC 3D, exclusive selection option with communication function         Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : 4+20mA DC 300Q or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C )         Load regulation ±0.0%, Resolution approx 1/50.000       Scaling function         Cutput limiter       : 0.0 - 100.0% (reverse setting is possible)         CT1+CT2 input       : In MAC 3D, exclusive selection option with DI-D2-D3         Detection method       : 25ms         Detection accuracy       : ±5%FS         Detection delay time       : 0.5 - 30.0 seconds         Alarm output       : Assigned to oUT1, OUT2, EV1, EV2, and EV3.		X Input range of master machine and slave machine should be equal, at the time of cascade control
Error detection       : None, Choose from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRC         Flow control       : none         Delay       : 1 - 500ms (resolution 1ms)         Communication code       : ASCII code or binary code         Protocol       : SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       : SUG (external connection)         Number of connection       : Maximum 32 sets (depends on conditions, host is included)         Analog output(AO)       : In MAC 3D, exclusive selection option with communication function         Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output kind       : d-20mA DC 300Q or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C )         Lead regulation ±0.05%, Resolution approx 1/50.000       E         Scaling function       : with (range depends on output type) analog output lower limit value < analog output upper limit value	Slave address	: 1-255
Flow control       : none         Delay       : 1 = 500ms (resolution 1ms)         Communication code       : ASCII code or binary code         Protocol       : SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       : 120Q (external connection)         Number of connection       : Maximum 32 sets (depends on conditions, host is included)         Analog output(AO)       : In MAC 3D, exclusive selection option with communication function         Output kind       : Choese from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : d + 200m A DC 300, Q roless, Display accuracy ± 0.3% (accuracy maintenance range 23°C±5°C )         Load regulation ± 0.05%, Resolution approx 1/50,000       E with (range depends on output type) analog output lower limit value < analog output upper limit value	Parameter preservation mo	ode: Choose from RAM, MIX and EEP mode.
Delay       ± 1 - 500ms (resolution 1ms)         Communication code       ± ASCII code or binary code         Protocol       ± SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       ± 120.2 (external connection)         Number of connection       ± Maximum 32 sets (depends on conditions, host is included)         Analog output (AO)       ± In MAC 3D, exclusive selection option with communication function         Output kind       ± Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       ± 4-20mA DC 300 Q or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C )         Load regulation±0.05%, Resolution approx 1/50,000       Load regulation±0.05%, Resolution approx 1/50,000         Scaling function       ± with (range depends on output type) analog output lower limit value < analog output upper limit value	Error detection	None, Choose from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRC
Communication code       : ASCII code or binary code         Protocol       : SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       : 120 Q (external connection)         Number of connection       : Maximum 32 sets (depends on conditions, host is included)         Analog output(AO)       : In MAC 3D, exclusive selection option with communication function         Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : 4-20mA DC 300 Q or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C )         Load regulation±0.05%, Resolution approx 1/50.000       Scaling function         Scaling function       : with (range depends on output type) analog output lower limit value < analog output upper limit value	Flow control	: none
Protocol       : SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol         Termination resistance       : 120Q (external connection)         Number of connection       : Maximum 32 sets (depends on conditions, host is included)         Analog output(AO)       : In MAC 3D, exclusive selection option with communication function         Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : 4-20mA DC 300 Q or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C)         Load regulation ±0.05%, Resolution approx 1/50.000       Scaling function         Scaling function       : with (range depends on output type) analog output lower limit value < analog output upper limit value	Delay	: 1 – 500ms (resolution 1ms)
Termination resistance       : 120Ω (external connection)         Number of connection       : Maximum 32 sets (depends on conditions, host is included)         Analog output(AO)       : In MAC 3D, exclusive selection option with communication function         Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : 4-20mA DC 300 Q or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C)         Load regulation±0.05%, Resolution approx 1/50,000         Scaling function       : with (range depends on output type) analog output lower limit value < analog output upper limit value	Communication code	: ASCII code or binary code
Number of connection	Protocol	SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol
Analog output(AO)       : In MAC 3D, exclusive selection option with communication function         Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : 4-20mA DC 300 Ω or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C )         Load regulation±0.05%, Resolution approx 1/50,000	Termination resistance	: 120 $\Omega$ (external connection)
Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : 4-20mA       DC 300 Ω or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C)         Load regulation±0.05%, Resolution approx 1/50,000       : with (range depends on output type) analog output lower limit value < analog output upper limit value	Number of connection	: Maximum 32 sets (depends on conditions, host is included)
Output kind       : Choose from PV, SV, OUT1, OUT2, CT1, and CT2.         Output rating       : 4-20mA       DC 300 Ω or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C)         Load regulation±0.05%, Resolution approx 1/50,000       : with (range depends on output type) analog output lower limit value < analog output upper limit value		
Output rating: 4-20mADC 300 Ω or less, Display accuracy ±0.3% (accuracy maintenance range 23°C±5°C ) Load regulation±0.05%, Resolution approx 1/50,000Scaling function: with (range depends on output type) analog output lower limit value < analog output upper limit value Output limiterOutput limiter: 0.0 - 100.0% (reverse setting is possible)CT1 · CT2 input: In MAC 3D, exclusive selection option with DI·D2·D3 Detection methodDetection method: Current judging system by CT sensor 	Analog output(AO)	: In MAC 3D, exclusive selection option with communication function
Load regulation ±0.05%, Resolution approx 1/50,000         Scaling function       : with (range depends on output type) analog output lower limit value < analog output upper limit value	Output kind	: Choose from PV, SV, OUT1, OUT2, CT1, and CT2.
Scaling function       : with (range depends on output type) analog output lower limit value < analog output upper limit value	Output rating	: 4–20mA $\ $ DC 300 $\Omega$ or less, Display accuracy $\pm 0.3\%$ (accuracy maintenance range 23°C $\pm 5$ °C $\ $ )
Output limiter: 0.0 - 100.0% (reverse setting is possible)CT1·CT2 input: In MAC 3D, exclusive selection option with DI·D2·D3Detection method: Current judging system by CT sensorDetection range: 0.0-55.0ASampling period: 125msDetection accuracy: ±5%FSDetection delay time: 0.5 - 30.0 secondsAlarm output: Assigned to eventDetection Objects: Assigned to OUT1, OUT2, EV1, EV2, and EV3.Alarm operating point: 0.0-50.0A		Load regulation $\pm$ 0.05%, Resolution approx 1/50,000
CT1 • CT2 input: In MAC 3D, exclusive selection option with DI•D2•D3Detection method: Current judging system by CT sensorDetection range: 0.0-55.0ASampling period: 125msDetection accuracy: ±5%FSDetection delay time: 0.5 - 30.0 secondsAlarm output: Assigned to eventDetection Objects: Assigned to OUT1, OUT2, EV1, EV2, and EV3.Alarm operating point: 0.0-50.0A	Scaling function	: with (range depends on output type) $$ analog output lower limit value $<$ analog output upper limit value
Detection method: Current judging system by CT sensorDetection range: 0.0-55.0ASampling period: 125msDetection accuracy: ±5%FSDetection delay time: 0.5 - 30.0 secondsAlarm output: Assigned to eventDetection Objects: Assigned to OUT1, OUT2, EV1, EV2, and EV3.Alarm output: 0.0-50.0A	Output limiter	: 0.0 - 100.0% (reverse setting is possible)
Detection method: Current judging system by CT sensorDetection range: 0.0-55.0ASampling period: 125msDetection accuracy: ±5%FSDetection delay time: 0.5 - 30.0 secondsAlarm output: Assigned to eventDetection Objects: Assigned to OUT1, OUT2, EV1, EV2, and EV3.Alarm output: 0.0-50.0A	CT1 · CT2 input	: In MAC 3D, exclusive selection option with DI•D2•D3
Detection range: 0.0-55.0ASampling period: 125msDetection accuracy: ±5%FSDetection delay time: 0.5 - 30.0 secondsAlarm output: Assigned to eventDetection Objects: Assigned to oUT1, OUT2, EV1, EV2, and EV3.Alarm operating point: 0.0-50.0A		
Detection accuracy       : ±5%FS         Detection delay time       : 0.5 - 30.0 seconds         Alarm output       : Assigned to event         Detection Objects       : Assigned to OUT1, OUT2, EV1, EV2, and EV3.         Alarm operating point       : 0.0-50.0A	Detection range	: 0.0–55.0A
Detection delay time       : 0.5 - 30.0 seconds         Alarm output       : Assigned to event         Detection Objects       : Assigned to OUT1, OUT2, EV1, EV2, and EV3.         Alarm operating point       .         setting range       : 0.0-50.0A	Sampling period	: 125ms
Alarm output       : Assigned to event         Detection Objects       : Assigned to OUT1, OUT2, EV1, EV2, and EV3.         Alarm operating point       .         setting range       : 0.0-50.0A	Detection accuracy	: ±5%FS
Detection Objects : Assigned to OUT1, OUT2, EV1, EV2, and EV3. Alarm operating point setting range : 0.0-50.0A	Detection delay time	: 0.5 - 30.0 seconds
Alarm operating point setting range : 0.0-50.0A	Alarm output	: Assigned to event
setting range : 0.0-50.0A	Detection Objects	: Assigned to OUT1, OUT2, EV1, EV2, and EV3.
	Alarm operating point	
Recommended CT sensors : Products of U_RD co., CTL-6-L ,CTL-6-V, CTL-6-P-H, CTL-6-S-H, CTL-12L-8	setting range	: 0.0-50.0A
	Recommended CT senso	rs : Products of U_RD co., CTL-6-L ,CTL-6-V, CTL-6-P-H, CTL-6-S-H, CTL-12L-8

General specification									
Data save	: By nonvolatile memory (EEPROM)								
Temporary dead time	: no influence within 0.02 second 100% dip								
Use environmental condition	: Temperature: -10~55 °C								
Humidity	: Below 90%RH (no dew condensation)								
Hight	: Altitude of 2000m or less								
Category	I								
Contamination degree	2								
Storage temperature Conditions : $-20\sim65$ °C									
Supply voltage	: 90-264V AC 50/60Hz or 21.6-26.4V AC (50/60Hz)/DC								
Power consumption	: 90-264V AC maximum 9VA 21.6-26.4V AC maximum 6 VA 21.6-26.4V DC maximum 4W								
Applicable standard Safety	: IEC1010-1 and EN61010-1:2001								
EMC : EN61326-1:1997+Amendment1:1998+Amendment2:2001									
(EMI: ClassA, EMS: AnnexA)									
	EN61000-3-2:2000 EN61000-3-3:1995 + Amendment 1:2001								

Oscillation	: IEC60068-2-6/1995						
Insulated class	: Class I apparatus						
Input noise removal ratio	: Normal 50dB or higher						
Impulse-proof noise	: Power-source Normal 100ns/1 $\mu$ s±1500V						
Insulation resistance	: Between input/output terminal and power supply terminal $~500V~$ DC $~20\Omega$ or higher						
	Between analog output or communication and other input/output terminals $500V$ DC $20\Omega$ or higher						
Withstand voltage	: Between input/output terminal and power supply terminal 1500V AC 1 minute or 1800V AC 1 second						
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		: Between analo	og output or communication a	nd other input/output terminals 500	OV AC 1 minute or 6	600V AC 1 second				
Resistance to vibration		: Frequency	10~ 55~10Hz, amplitude	0.75mm (one side amplitude )•••10	0m/S <sup>2</sup> Direction	3 directions				
Sweep speed 1 octave/minute (about 5 minutes for both-way/cycle) Number of sweep 10 times										
Case material PPO or PPE										
Case color : Light gray (Mansel value 3.73B7.77/0.25)										
Outside dimension MAC3 A : H96 × W96 × D69mm (depth in panel 65mm)										
MAC3 B : H96 × W48 × D66mm (depth in panel 62mm)										
MAC3C : H72 × W72 × D62mm (depth in panel 62mm)										
MAC3 D : H48 × W48 × D66mm (depth in panel 62mm)										
Thickness of	applied panel	: 1.2-2.8mm								
Size of attach	ment hole									
	MAC3A	: H92 × W92mm	Attachment hole size of ho	rizontal plural proximity attachment	W(96 × N−4) mm	H92mm				
	MAC3B	: H92 × W45mm		N=number of equipment	W(48 × N−3) mm	H92mm				
	MAC3C	: H68 × W68mm			W(72 × N−4) mm	H68mm				
	MAC3D	: H45 × W45mm			W(48 × N−3) mm	H45mm				
Weight	MAC3A	: About 220g :								
	MAC3B	: About 160g								
	MAC3C	: About 160g								
	MAC3D	: About 120g								
Isolation : Except for input, system and contact, all control output are no-isolation										
	Be	tween event output B	EV1 and EV2 1 is not insulate	d						
Others are basic insulation or functional insulation.										
Refer to the following insulation block chart.										
	Insulation bloc	ck chart								
	Ba	asic I nsulation —	Functional insulation	Not insulated						
			Power	supply						

System

Measurement input (PV)

External control input 1 (DI1)

External control input 2 (DI2)

External control input 3 (DI3)

External control input 4 (DI4)

Current transformer 1 (CT1)

Current transformer 2 (CT2)

Control output 1 (contact)

Control output 2 (contact)

Event output 1 (EV1)

Event output 2 (EV2)

Event output 3 (EV3)

Analog output (AO)

Communication

Control output 1 (a voltage pulse / current)

Control output 2 (voltage pulse / current)



## 9. Program pattern setting table

Start mode SV, PV										
End step 1-25										
Number of pattern execution 1~9999, $\infty$										
100%										
Time unit: min.: sec., hour: min., or hour										
Output1 PID No.1										
P= %										
I= second	90									
D= second										
Differential gap =										
Manual reset = %										
Output limiter OL= %										
OH= %	80									
Output 1 PID No.2	00									
P= %										<b> </b>
I= second										<b>├────</b> ┃
D= second										<b> </b>
Differential gap =	70									<b>  </b>
Manual reset = %										
Output limiter OL= %										
OH= %										ļ
Output 1 PID No.3										
P= %	60									
I= second										
D= second										
Differential gap =										
Manual reset = %										
Output limiter OL= %	50									
OH= %										
Output 2 PID No.1										
P= %										
I= second										
D= second	40									
Differential gap =										
Manual reset = %										
Output limiter OL= %										
OH= %										
Output 2 PID No.2	30									
P= %										┝────┦
I= second										
D= second										
Differential gap =	20									
Manual reset = %	20									
Output limiter OL= %										
OH= %										
Output 2 PID No.3										
P= %										
I= second	10									ļl
D= second										
Differential gap =										
Differential gap =										
Output limiter OL= %										
OH= %										
Step No.										
SV (target setting value)										
Time										
Output 1 PID No.										
Output 2 PID No.										
								1		

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The contents of this instruction are subject to change without notice.

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